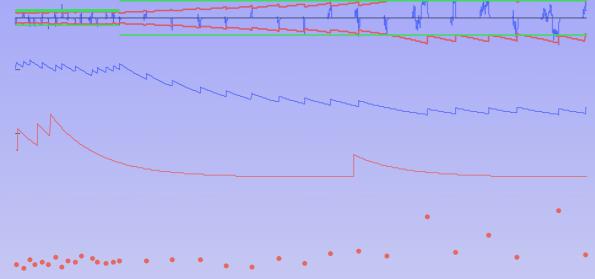
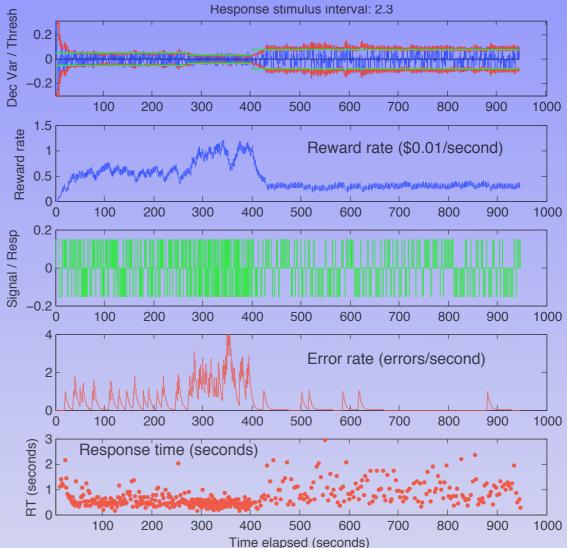
Adaptive performance in two-alternative decision making



Patrick Simen

Collaboration with Phil Holmes and Jonathan D. Cohen Princeton University



Deciding, by drift and diffusion

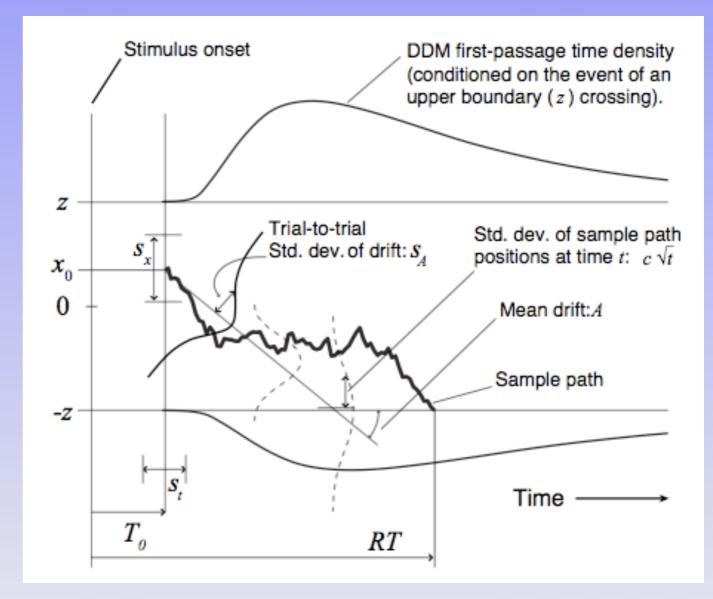
Continuous time:

$$dX = A \, dt \, + \, \sigma dW$$

Discrete time (a random walk):

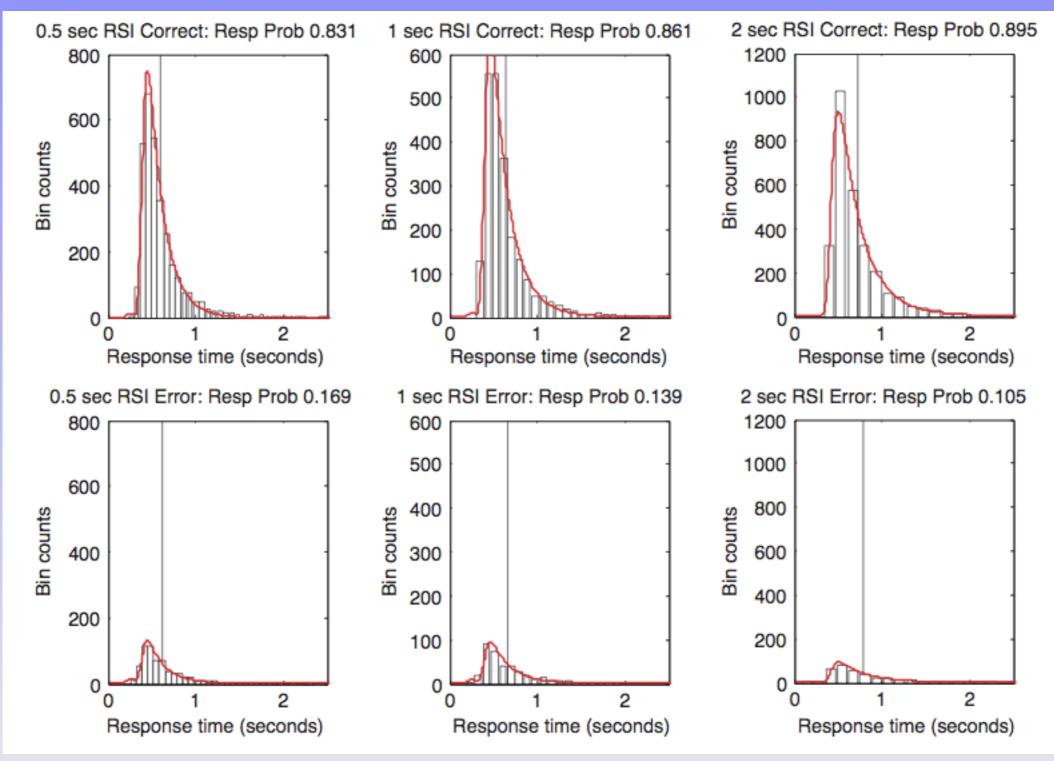
$$\begin{aligned} X_{new} &= X_{old} + \dots \\ A \cdot \Delta_t + \dots \\ \sigma \cdot \sqrt{\Delta_t} \cdot \xi, \end{aligned}$$

with ξ standard normal



cf. Ratcliff & Rouder (1998) Psych Science

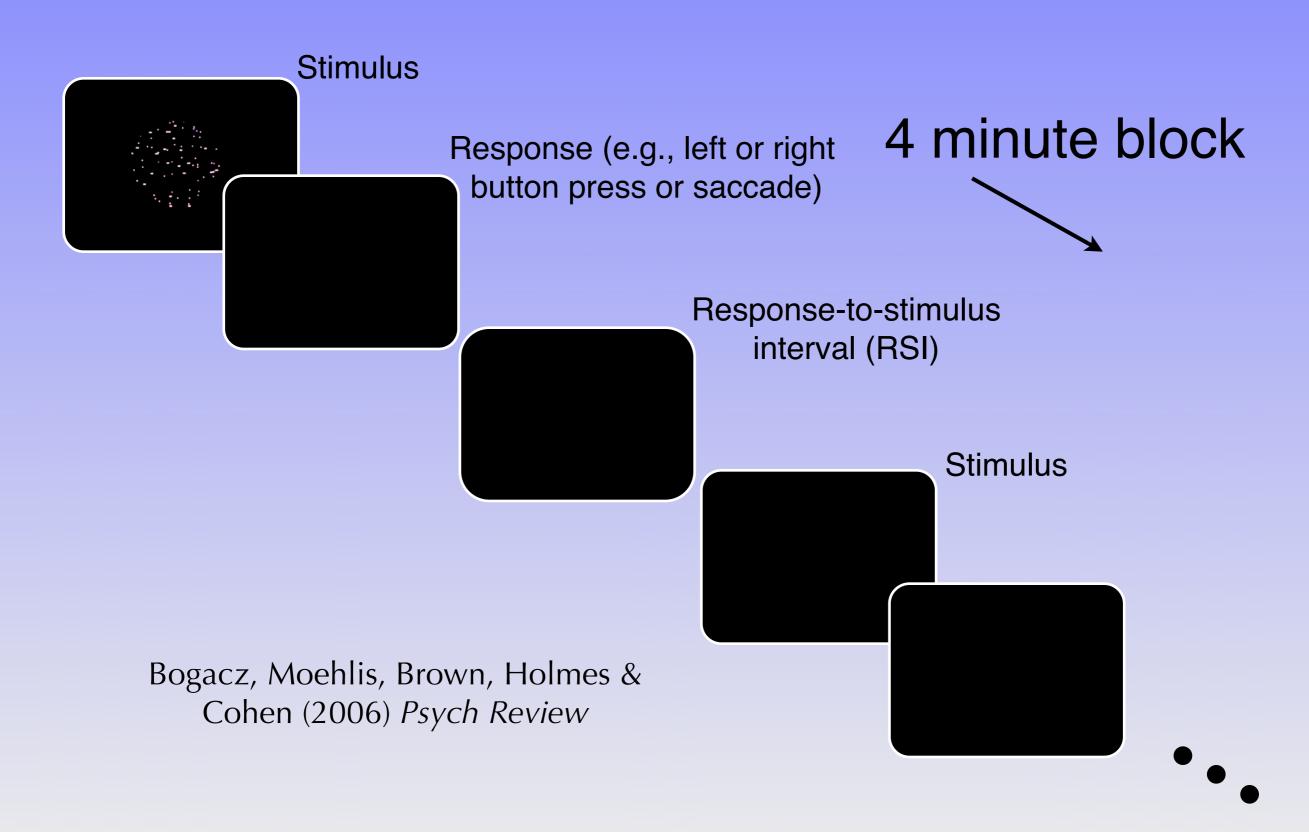
Fits data well

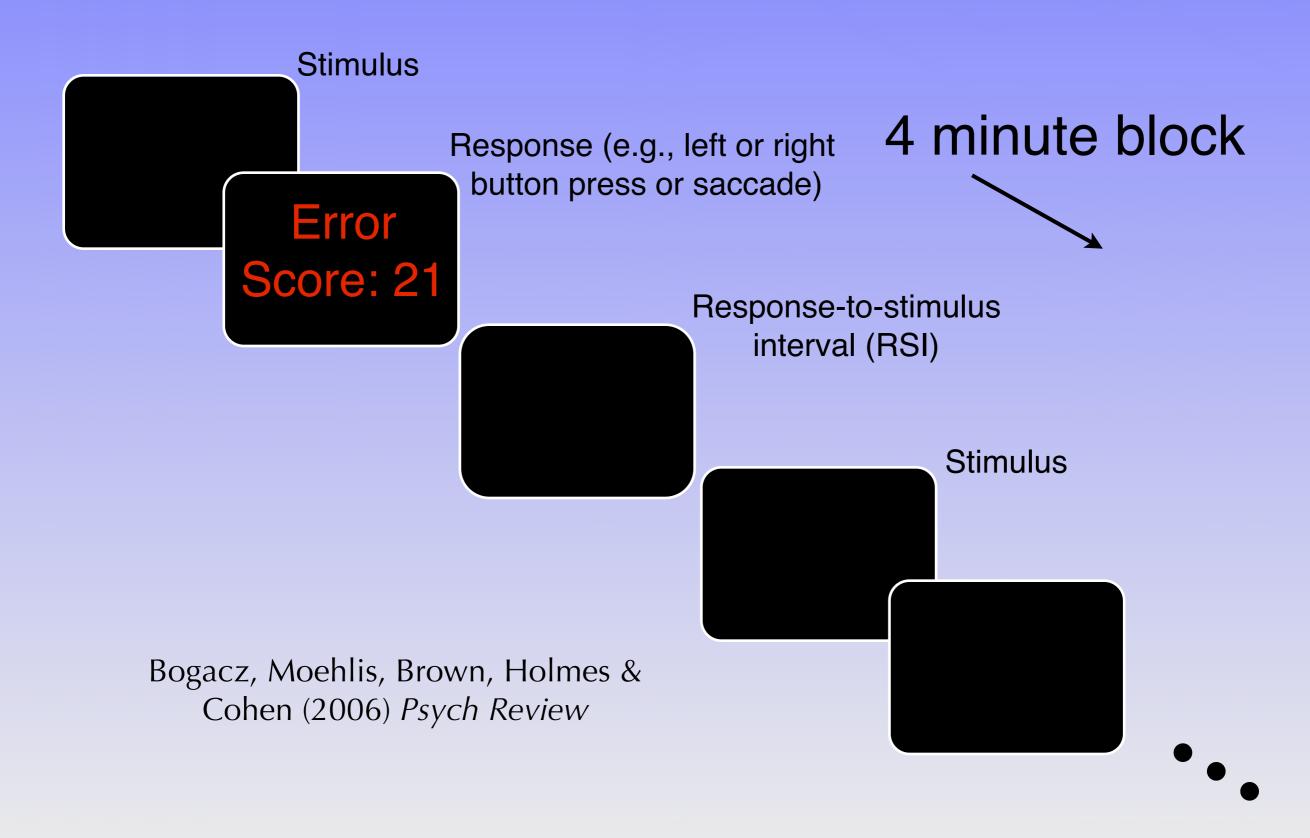


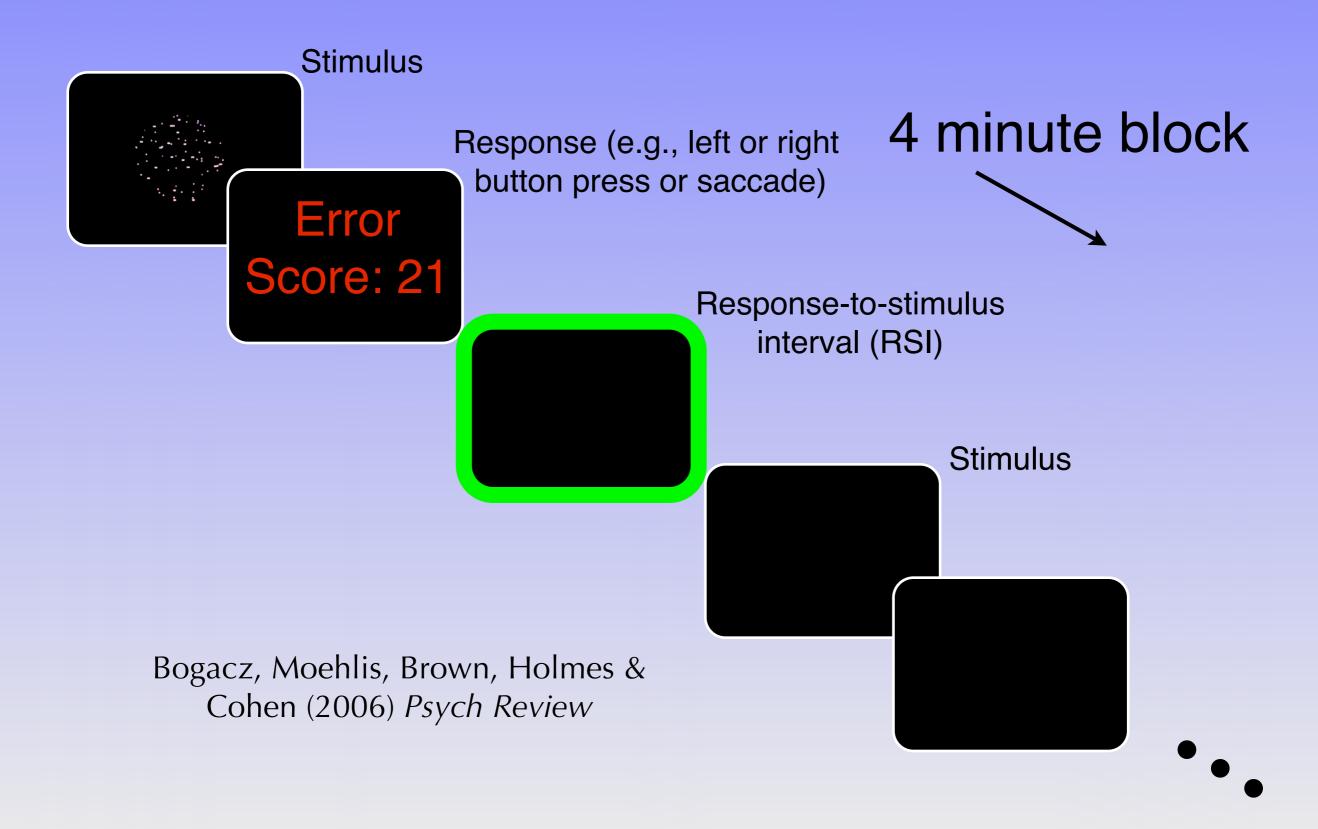
Simen, Contreras, Buck, Hu, Holmes & Cohen (in press), J Exp Psych: Human Perception & Performance

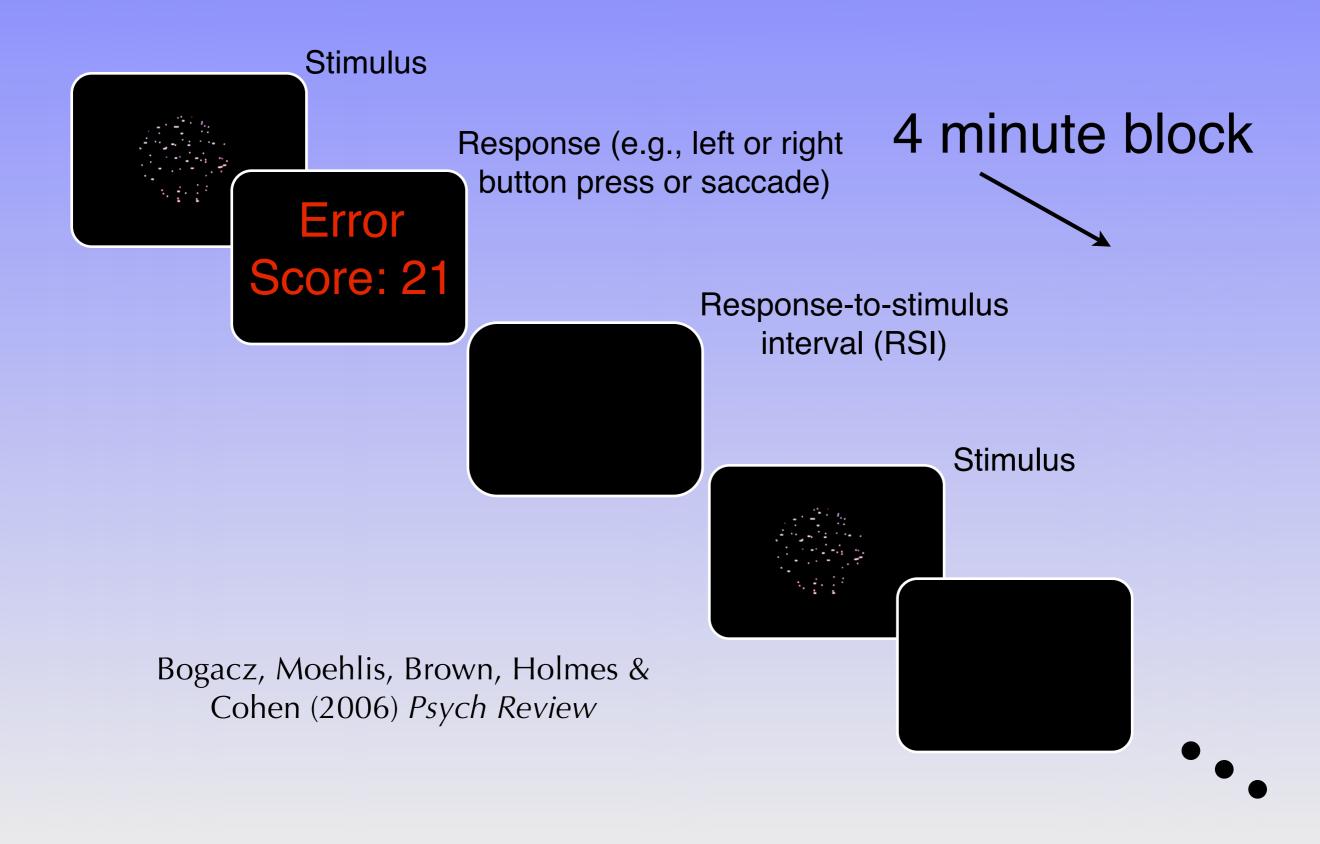
Outline

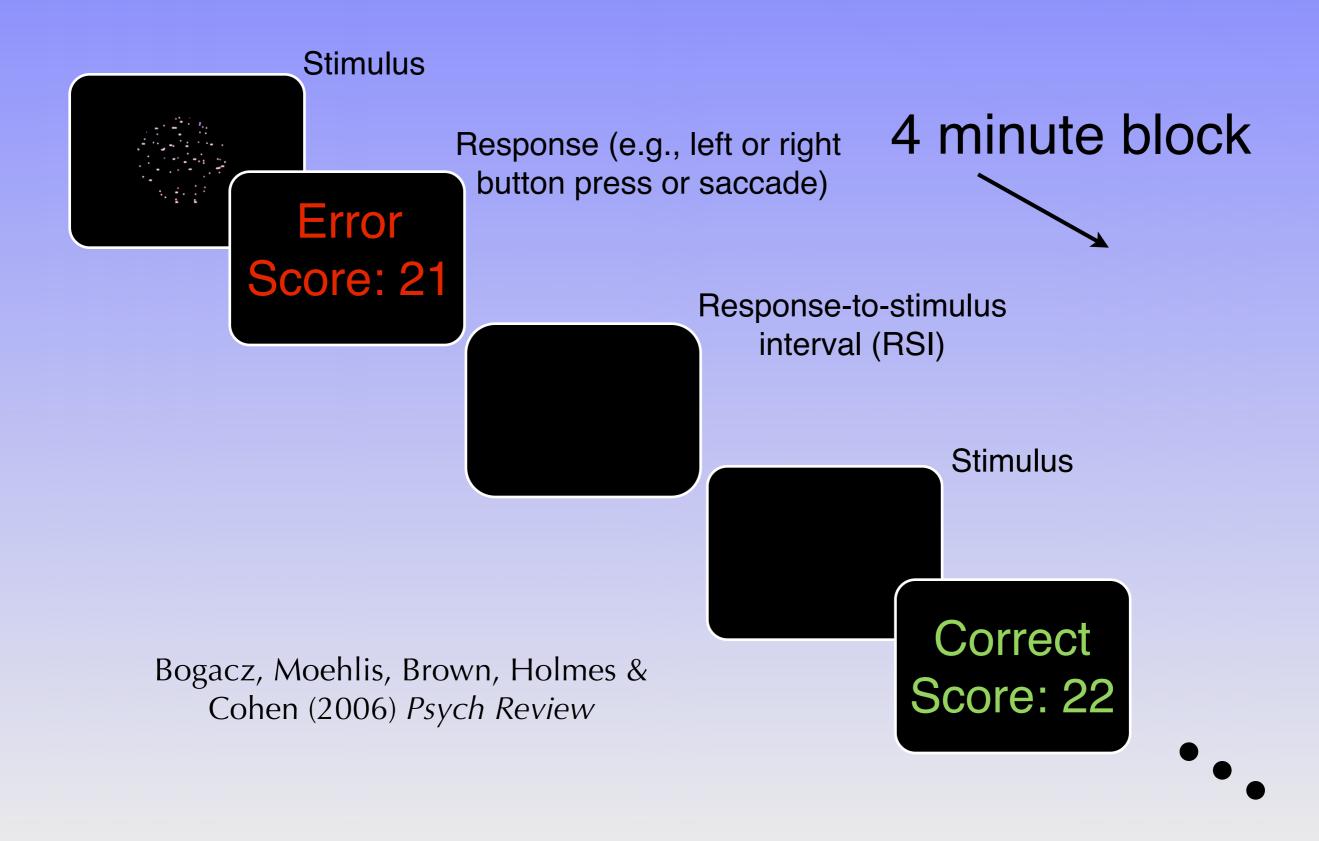
- Can simple conditioning/RL principles determine parameter specification in a "neurally plausible" implementation of this decision-making model?
- Optimal (reward maximizing) behavior statistics can be efficiently predicted for a simple, generic task that mimics life in a Skinner box.
- People seem to exhibit the predicted average behavior in this task; they also appear to implement a very simple learning algorithm for discovering nearly optimal model parameters.











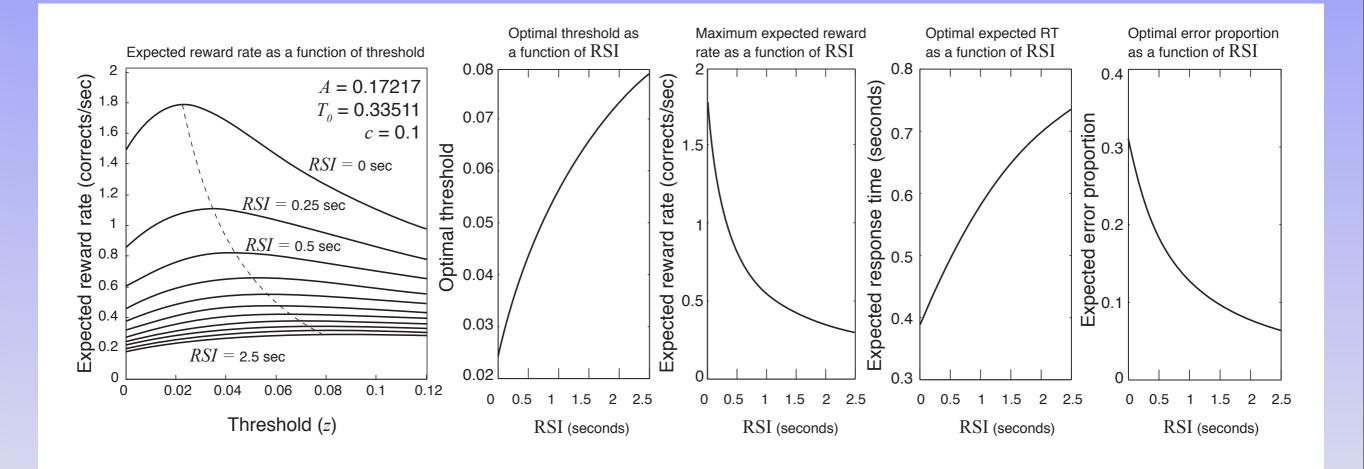
Reward-maximizing performance: predictions of Bogacz, Moehlis, Brown, Holmes & Cohen (2006) *Psych Review*

Q: What's the very best an ideal observer could do in a 2AFC task with rewards for corrects, no rewards for errors?

A: Reduce Ratcliff's diffusion model to Stone's sequential probability ratio test (SPRT) model by setting its extra parameters to 0, and feed it samples of log likelihood information.

Set starting point and threshold so as to maximize expected reward (cf. Edwards, 1965 and Link, 1975)

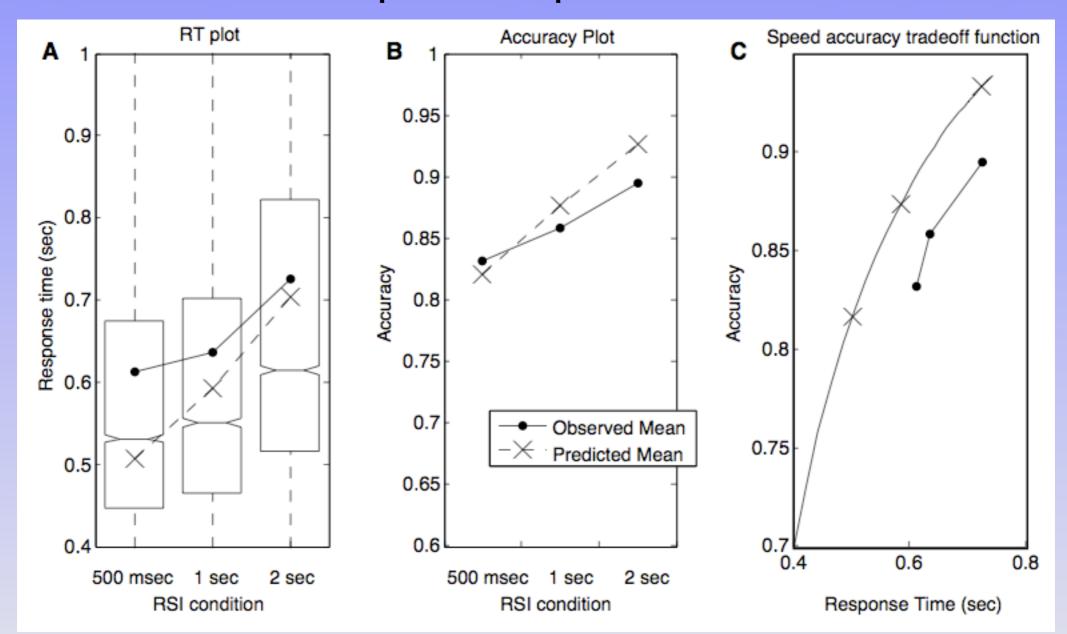
Optimal response to changes in RSI: adapt threshold as follows



Simen, Contreras, Buck, Hu, Holmes & Cohen (in press), Journal of Experimental Psychology: Human Perception & Performance

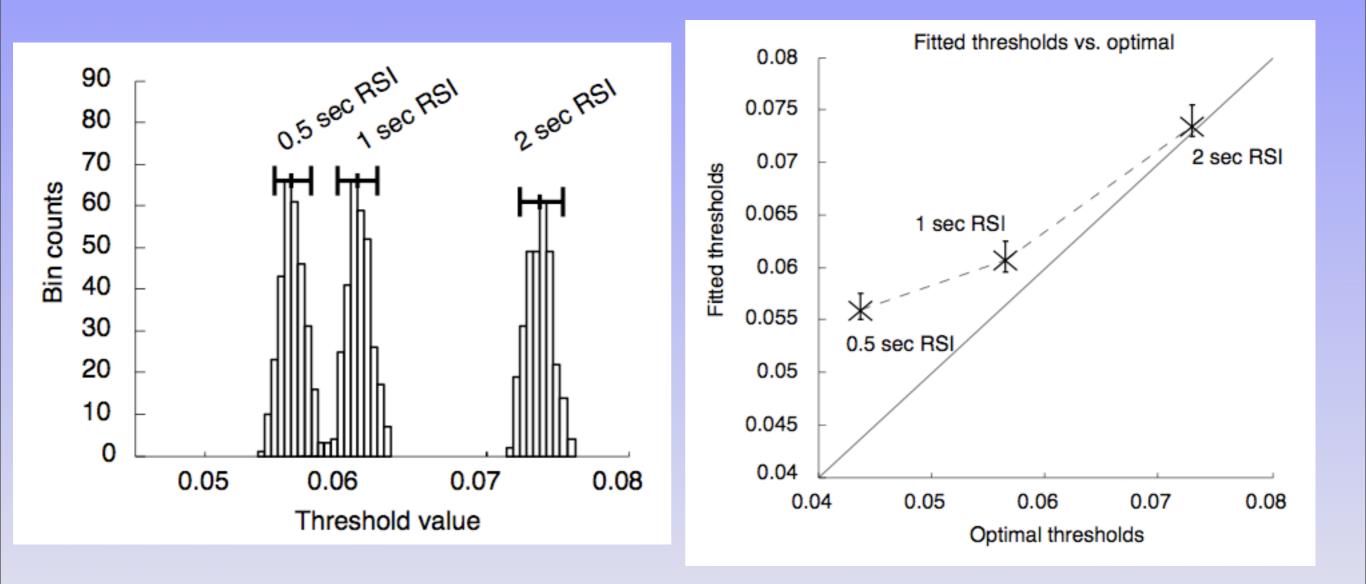
Human performance in **Expt 1**: moving dots, blocked by RSI = {0.5, 1, 2} sec, left and right button

press responses

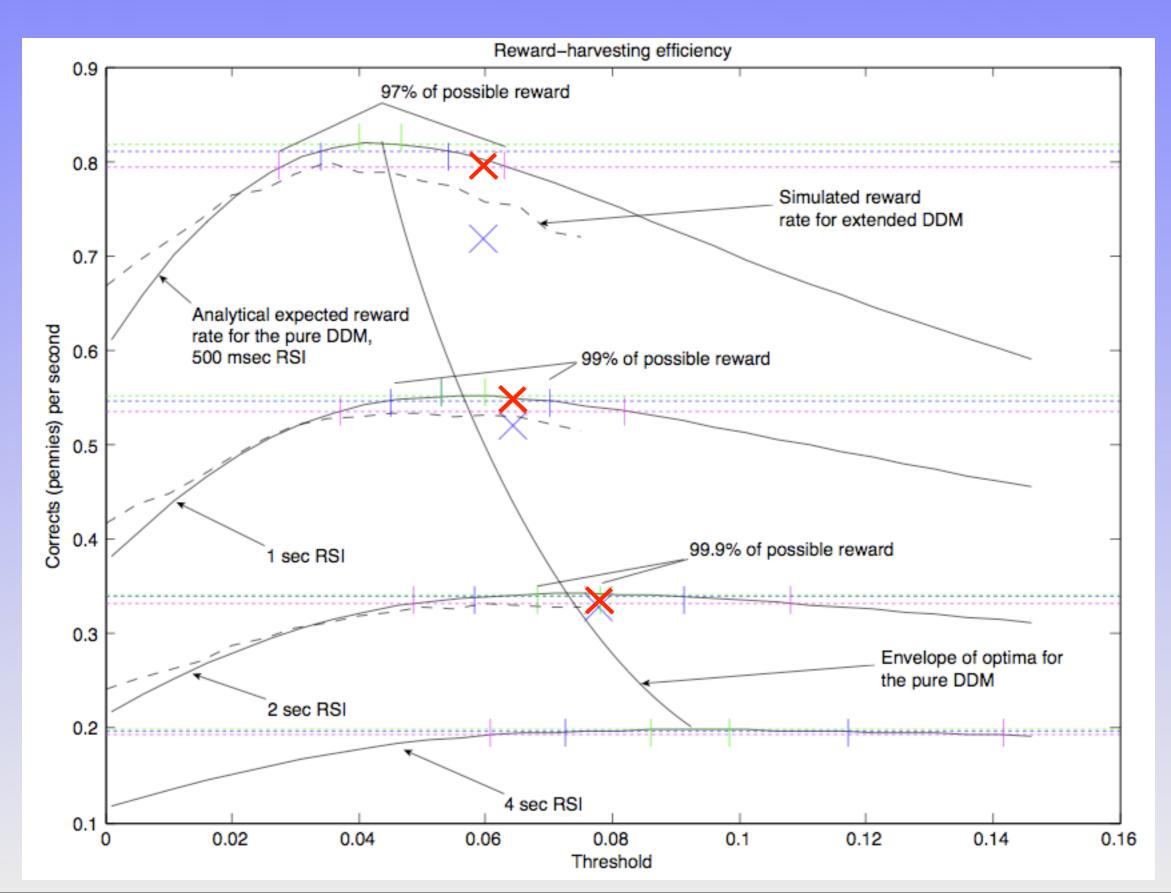


Simen, Contreras, Buck, Hu, Holmes & Cohen (in press), Journal of Experimental Psychology: Human Perception & Performance

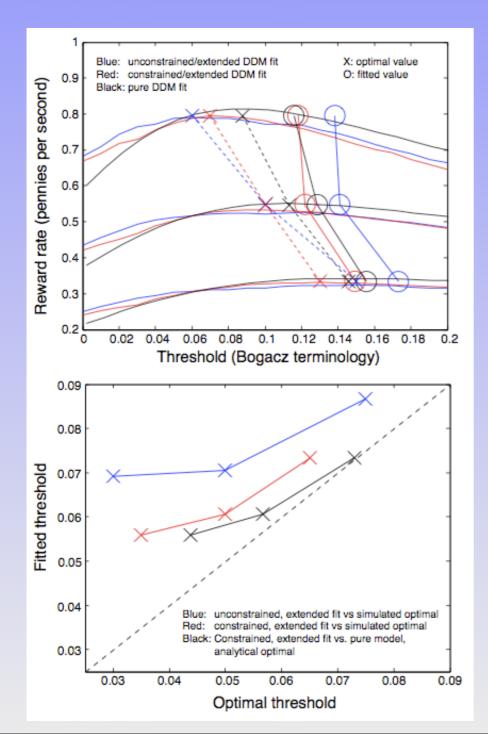
Observed threshold changes in **Expt 1** vs. optimal changes

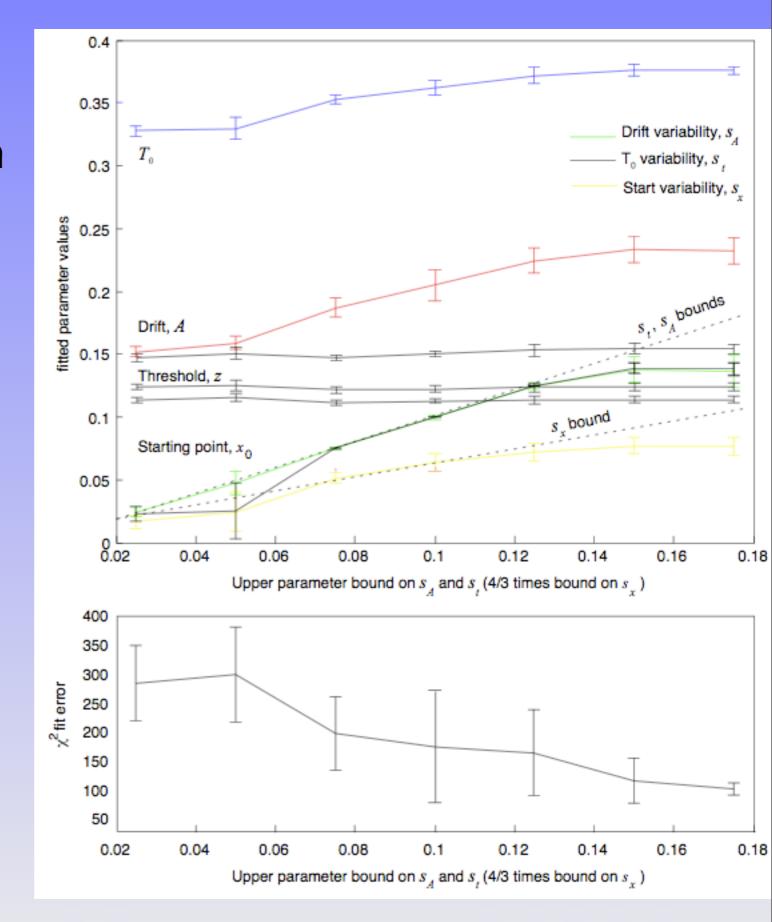


Expt 1: People are very good

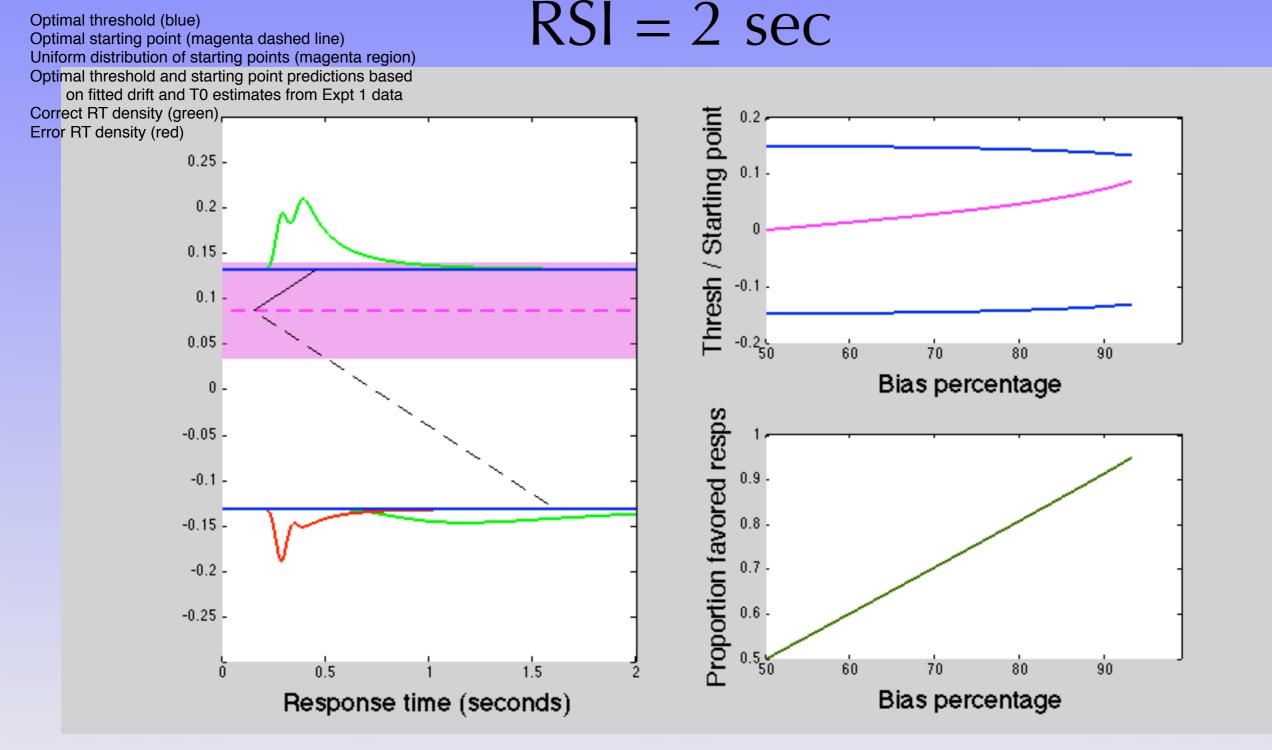


Constrained fitting (bounding s_t, s_A, s_z) gives better account of data than unconstrained fits

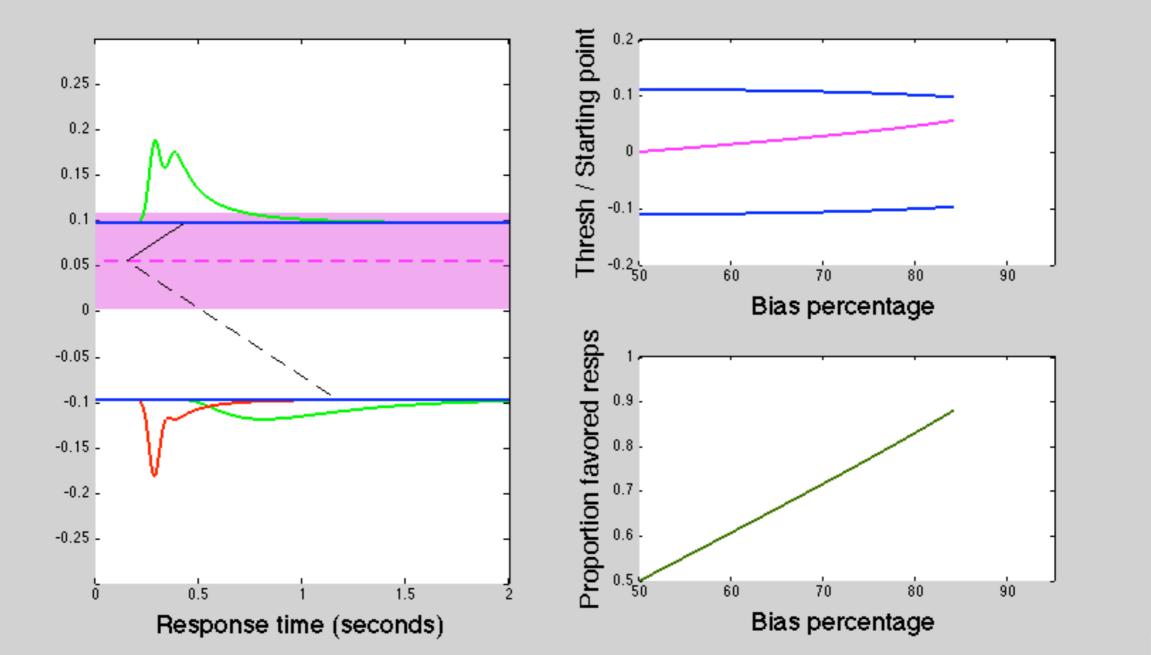




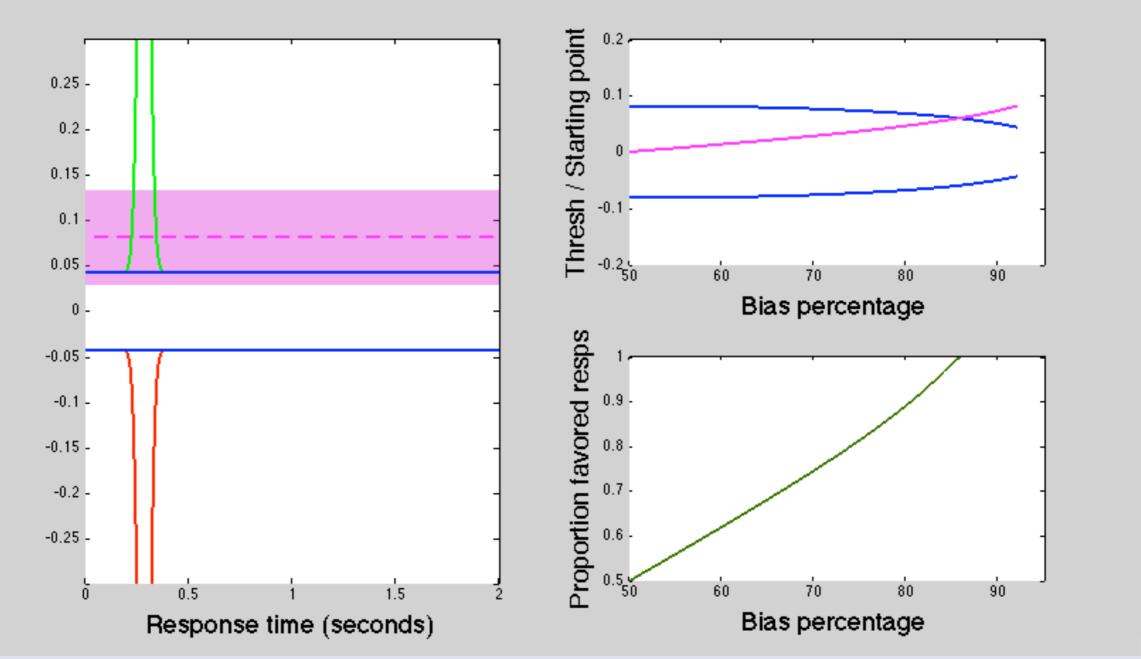
Optimal threshold and starting point parameterization and resulting behavior for unequal stimulus odds (50:50 --> 99:1)

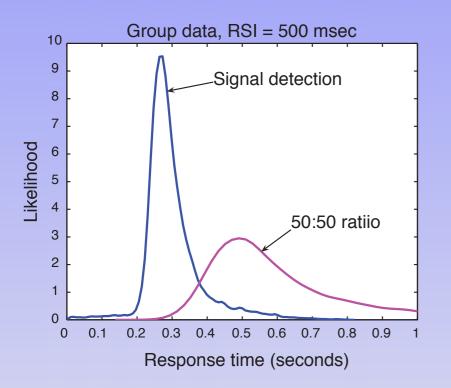


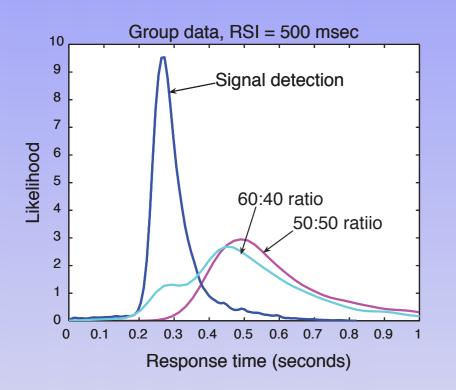
Unequal stimulus odds (50:50 --> 99:1) RSI = 1 sec

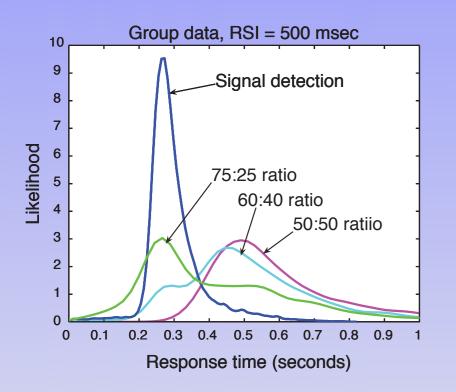


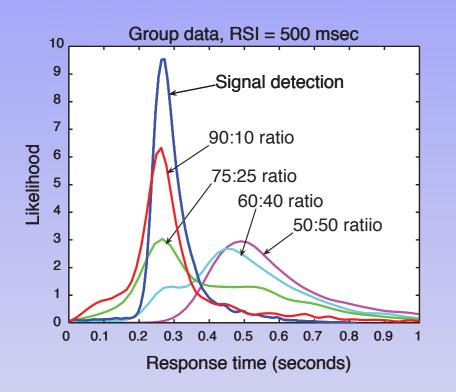
Unequal stimulus odds (50:50 --> 99:1) RSI = 0.5 sec

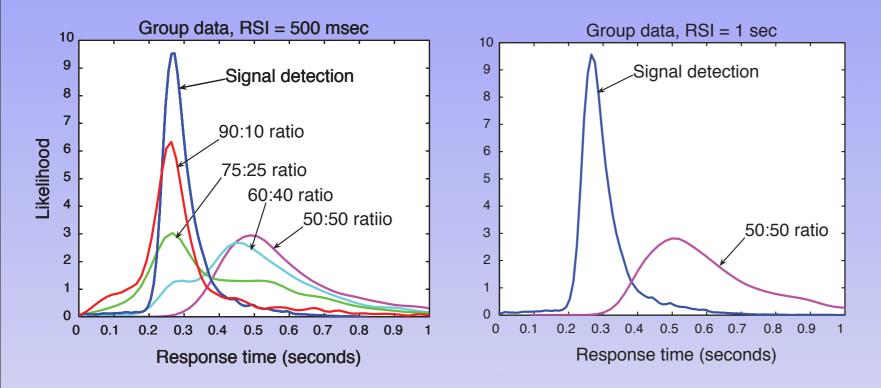


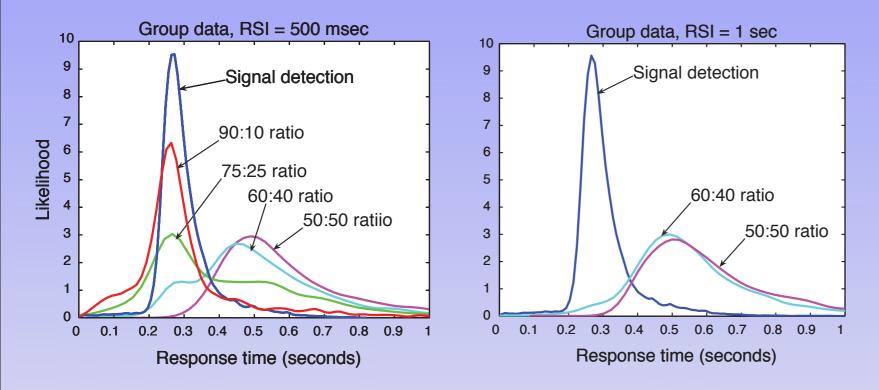


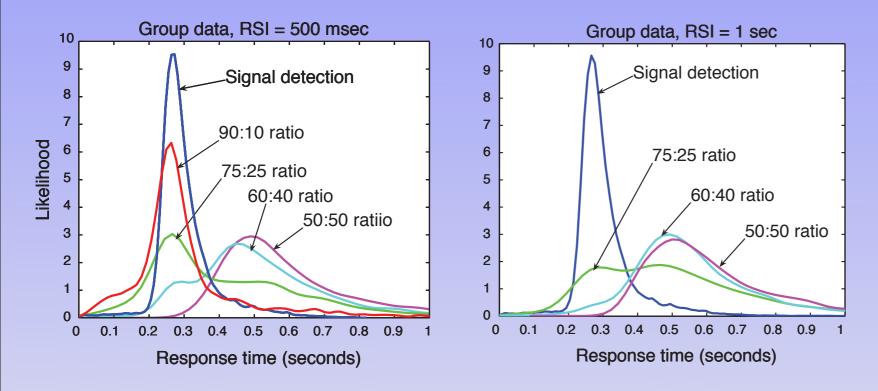


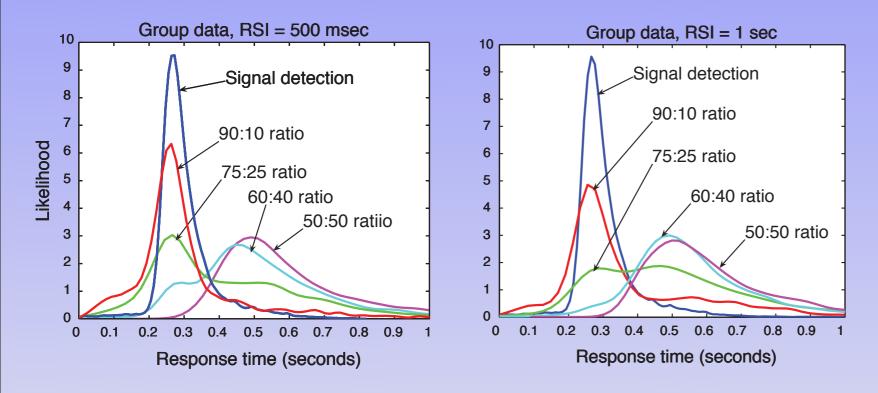


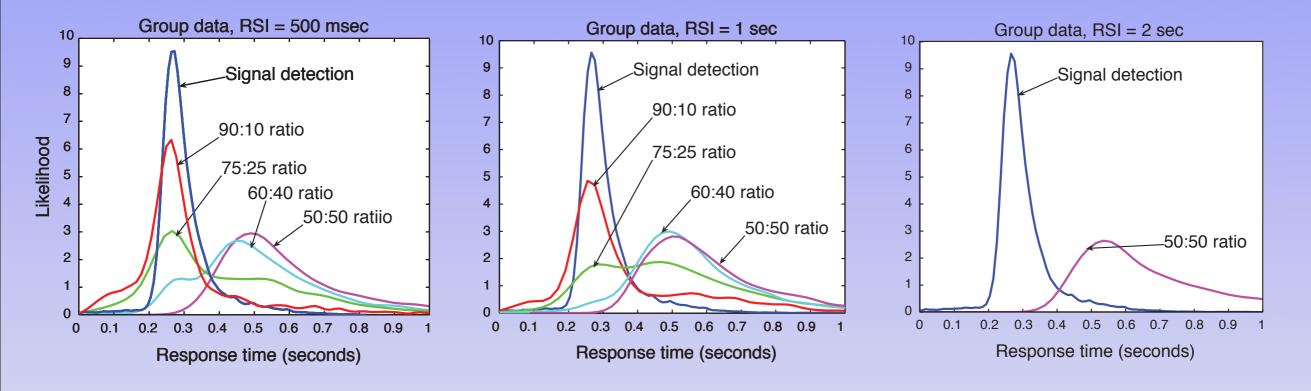


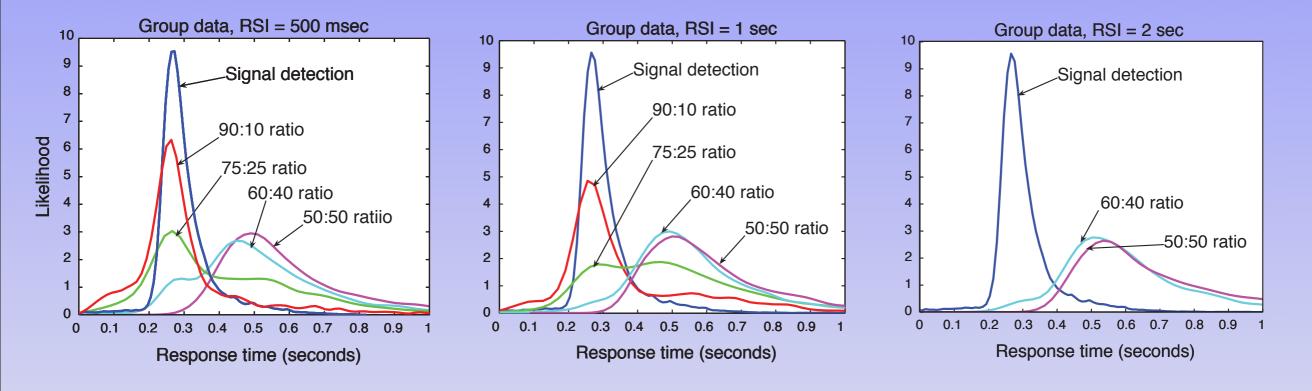


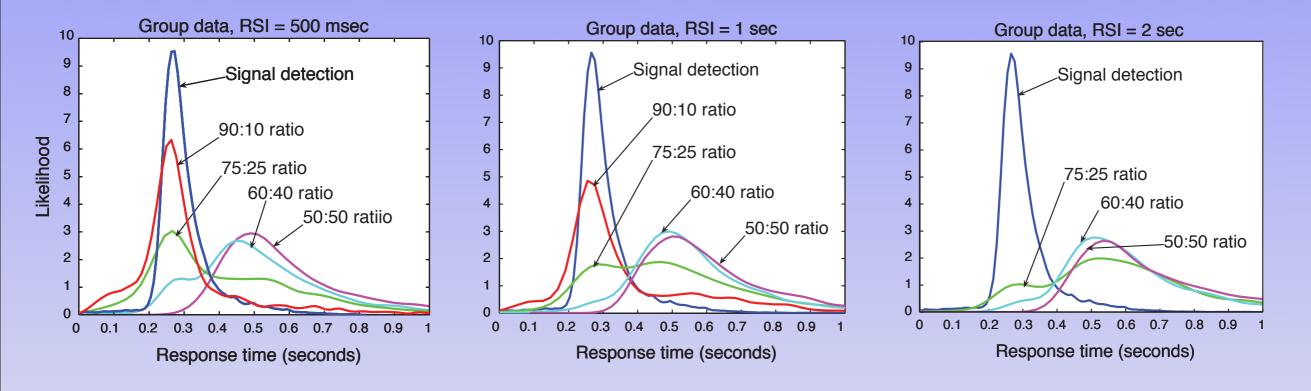


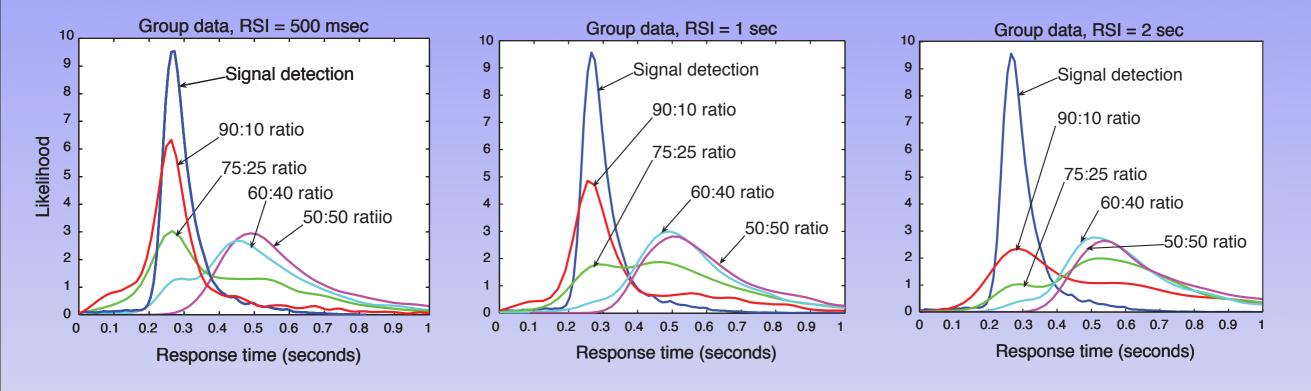




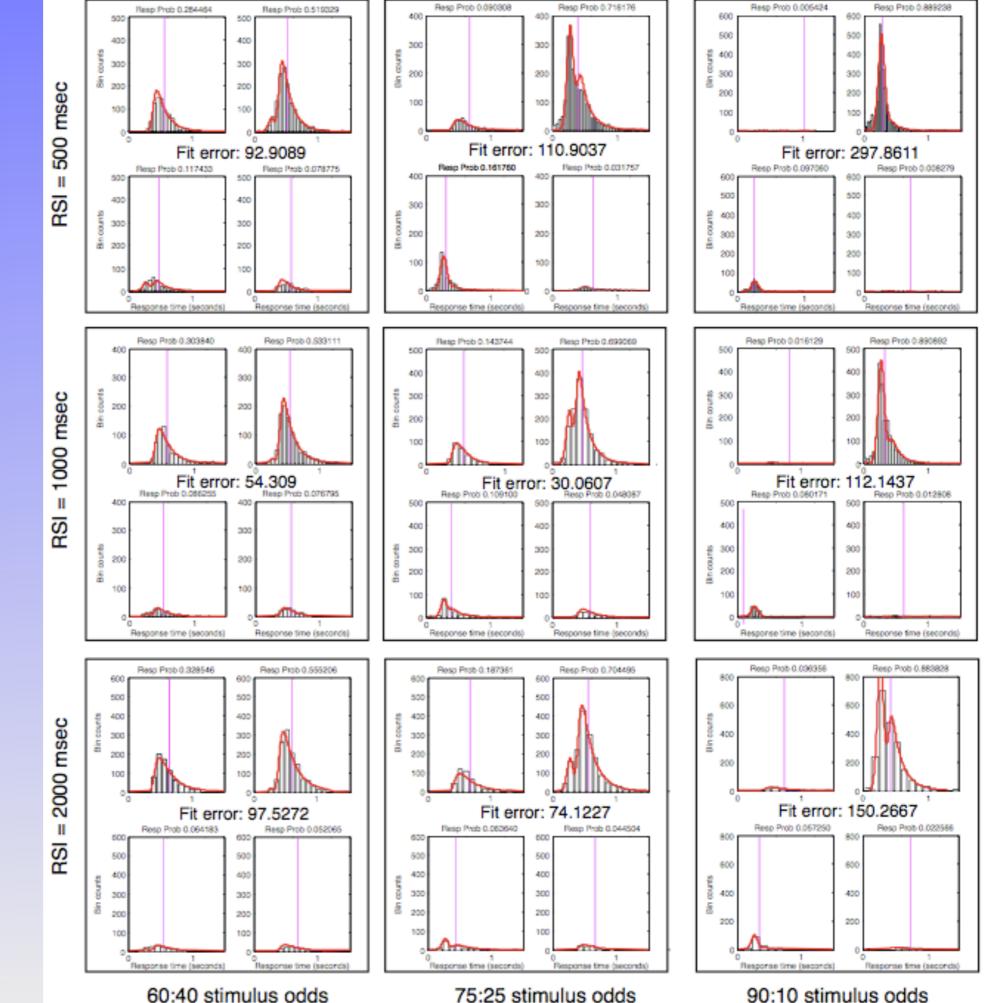




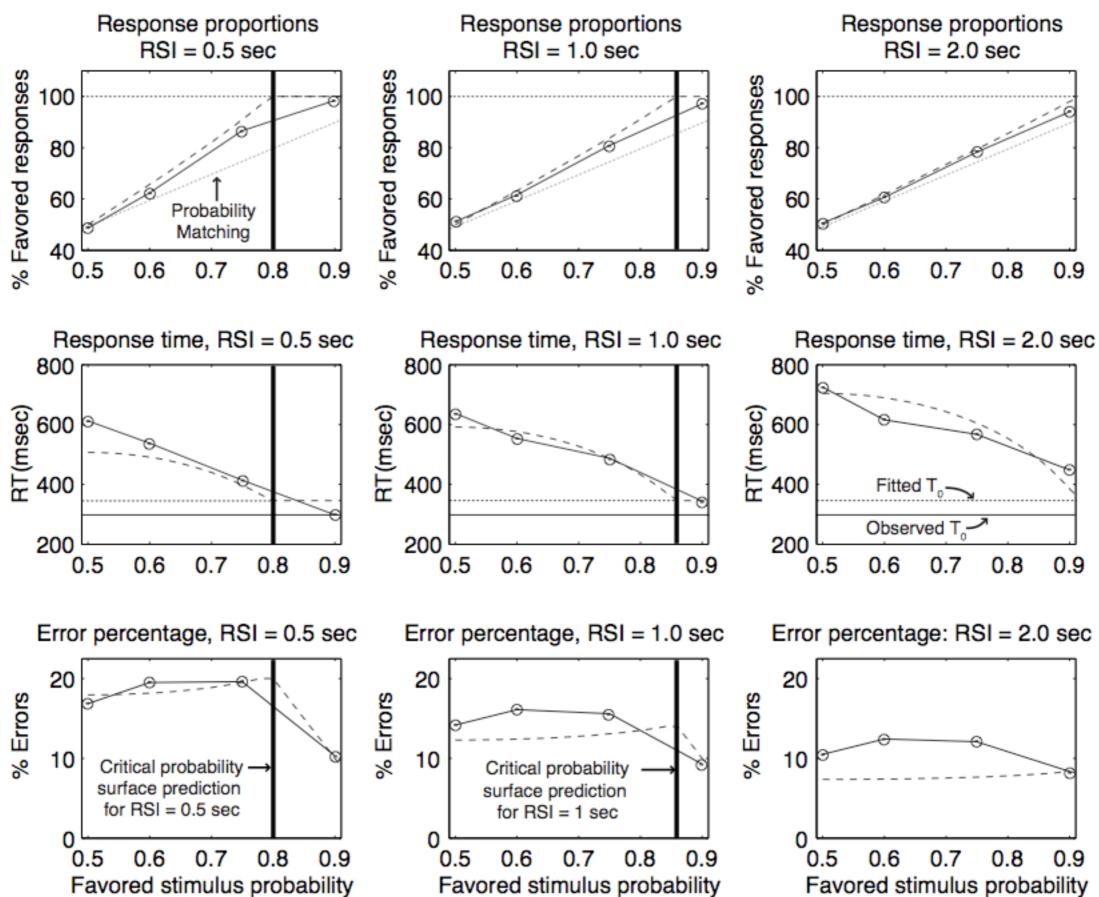




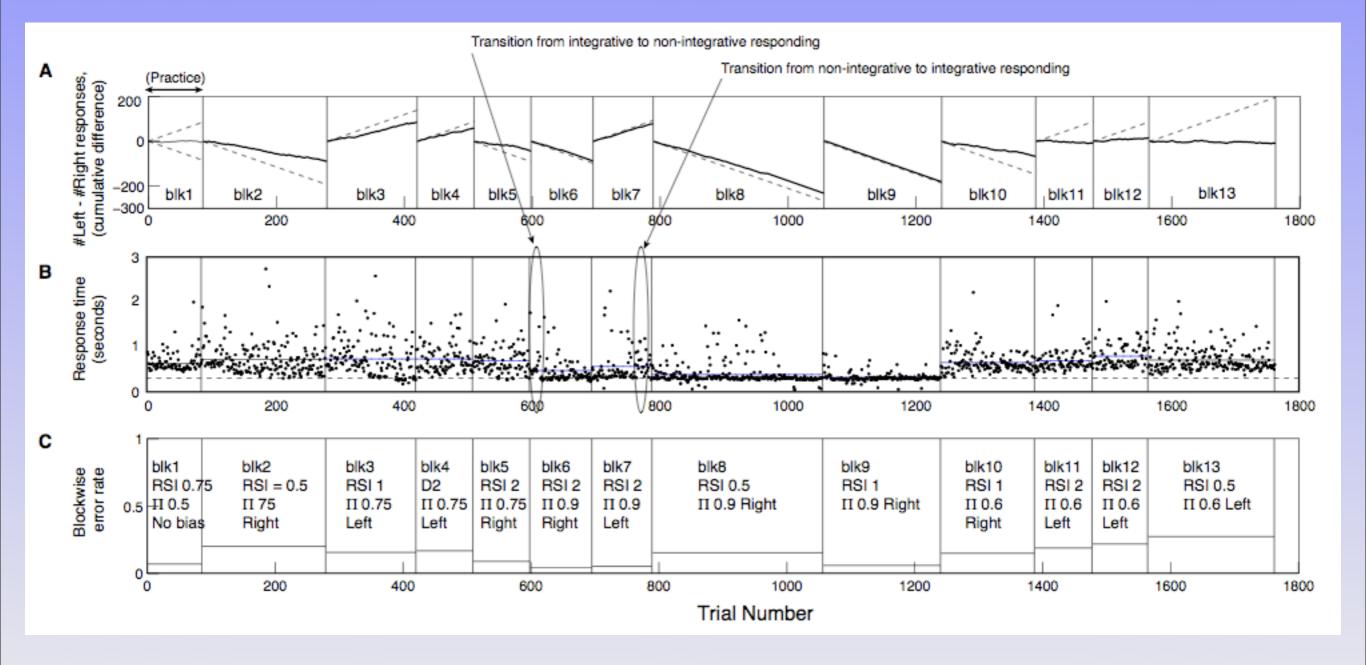
Mixture model fits (red) vs. empirical (black histograms)



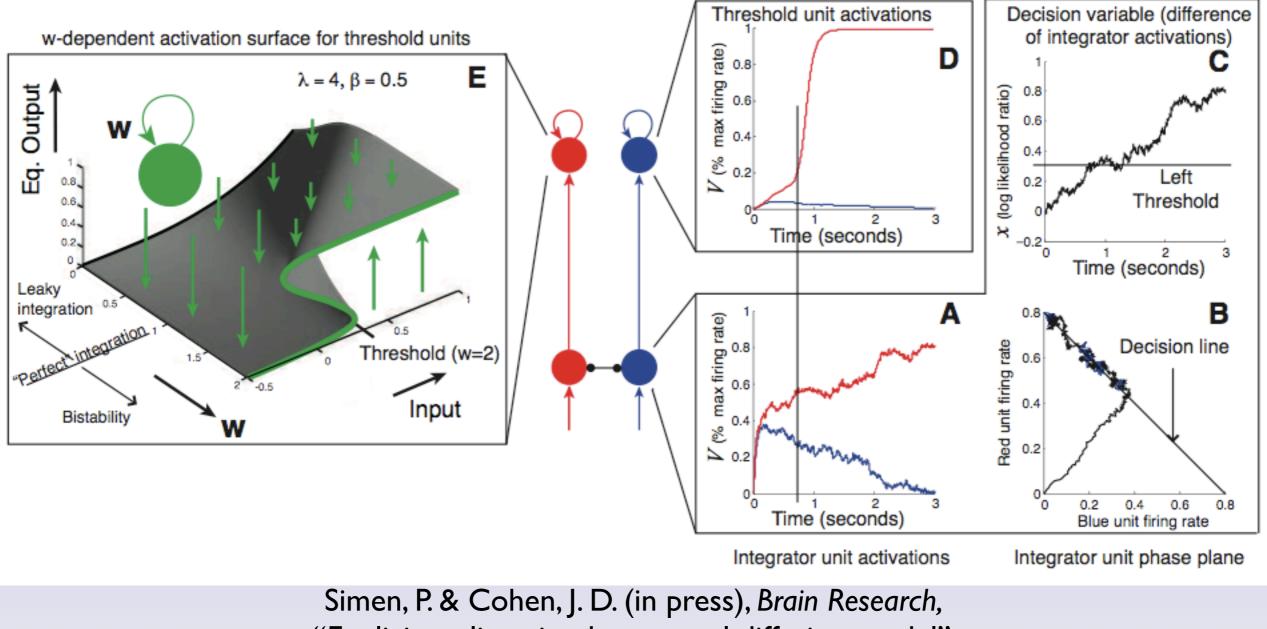
Predicted (dashed), observed (solid lines, circle data pts.)



Trial-by-trial performance, for one subject, **Expt 2**



Neural circuit that also does "matching"



"Explicit melioration by a neural diffusion model"

Neural circuit that also does "matching"

Threshold unit activations Decision variable (difference of integrator activations) max firing rate) D 0.8 0.8 (log likelihood ratio) 0.6 0.6 0.4 0.4 % 0.2 Left 0.2 Threshold 2 з × Time (seconds) -0.2 1 2 3 Time (seconds) В max firing rate) Decision line Red unit firing rate 0.8 0.6 0.6 0.4 0.4 2 0.2 A 0.2 2 0.2 0.4 0.6 0.8 0 Time (seconds) Blue unit firing rate

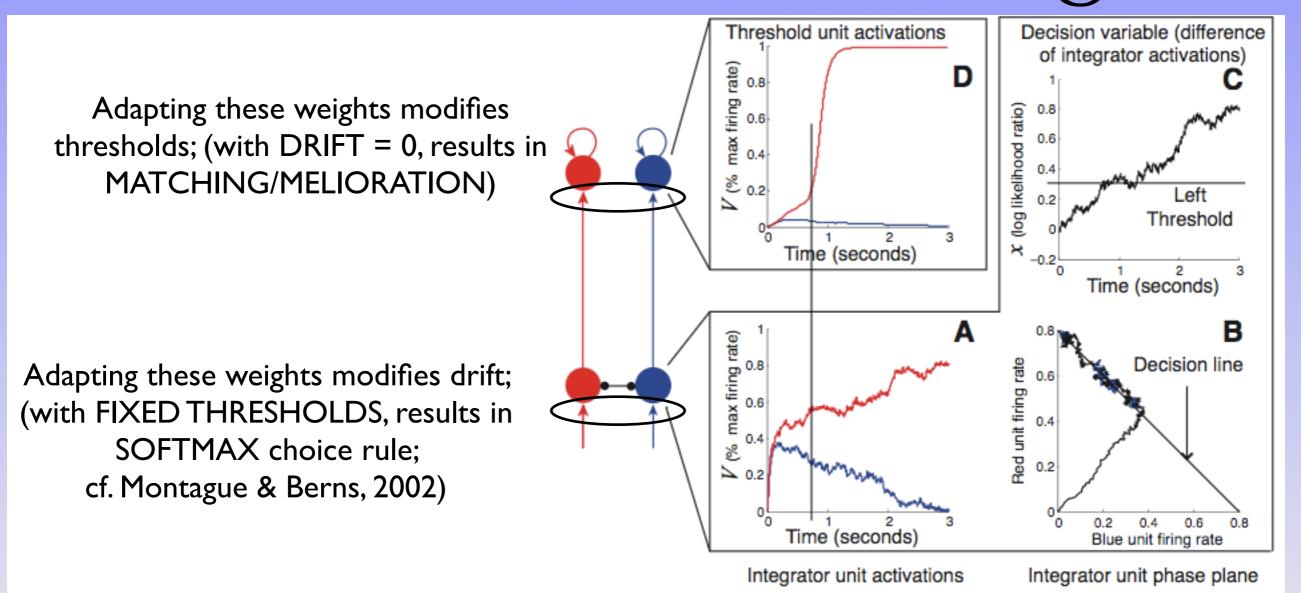
Adapting these weights modifies drift; (with FIXED THRESHOLDS, results in SOFTMAX choice rule; cf. Montague & Berns, 2002)

Integrator unit activations

Integrator unit phase plane

Simen, P. & Cohen, J. D. (in press), *Brain Research,* "Explicit melioration by a neural diffusion model"

Neural circuit that also does "matching"



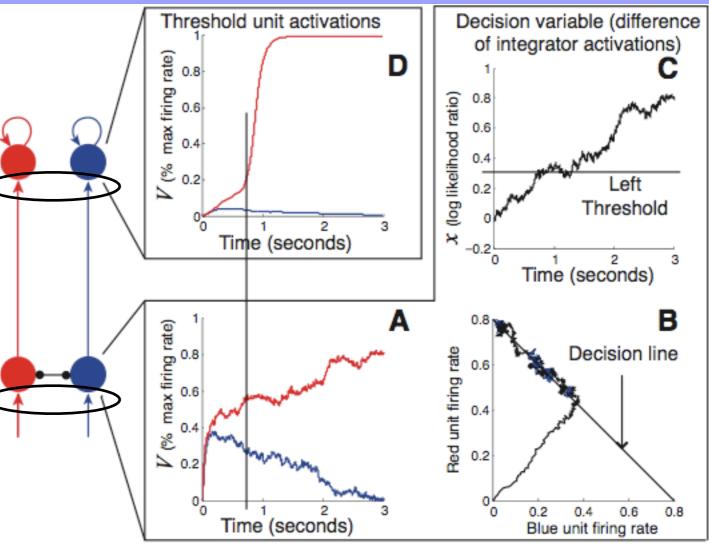
Simen, P. & Cohen, J. D. (in press), *Brain Research*, "Explicit melioration by a neural diffusion model"

Neural circuit that also does "matching"

Adapting these weights modifies thresholds; (with DRIFT = 0, results in MATCHING/MELIORATION)

$$\dot{w}_i = -w_i(t) + r_i(t)$$

Adapting these weights modifies drift; (with FIXED THRESHOLDS, results in SOFTMAX choice rule; cf. Montague & Berns, 2002)



Integrator unit activations

Integrator unit phase plane

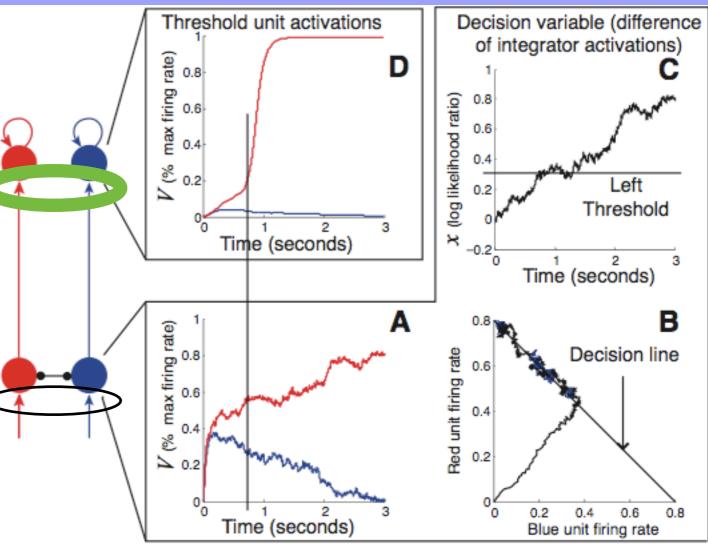
Simen, P. & Cohen, J. D. (in press), *Brain Research,* "Explicit melioration by a neural diffusion model"

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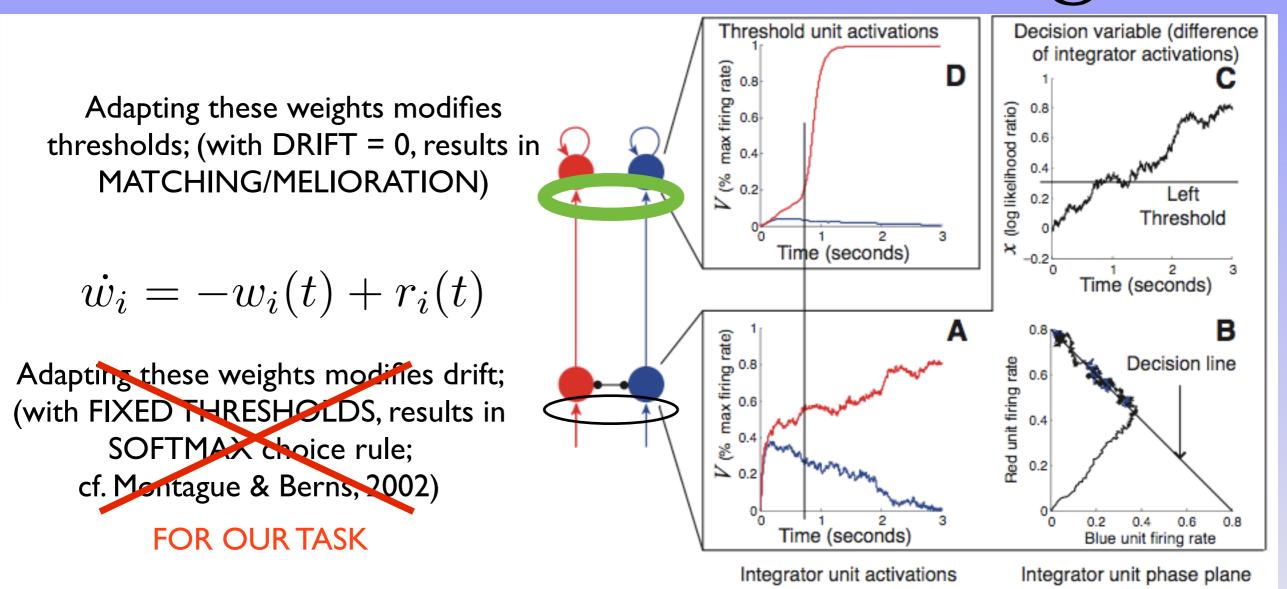


Integrator unit activations



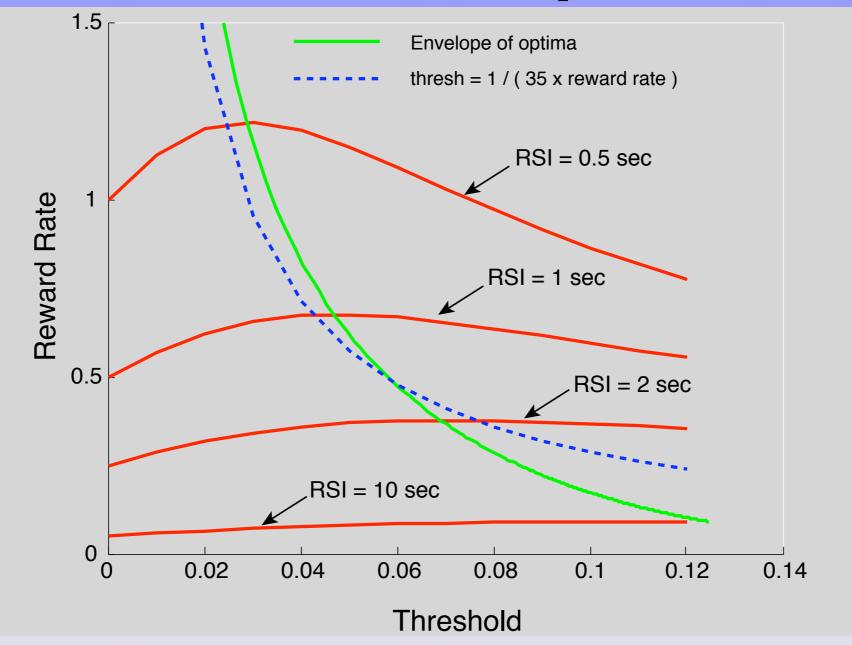
Simen, P. & Cohen, J. D. (in press), *Brain Research,* "Explicit melioration by a neural diffusion model"

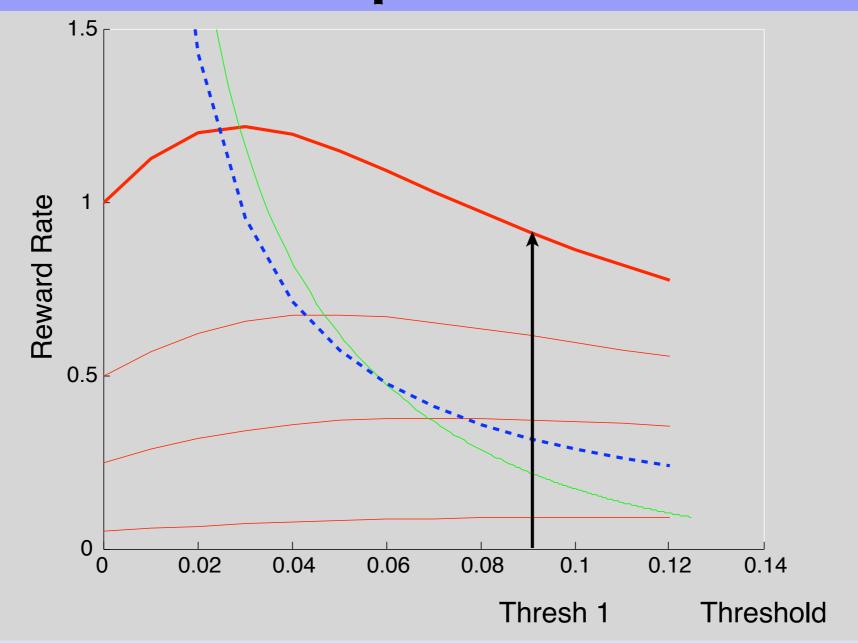
Neural circuit that also does "matching"

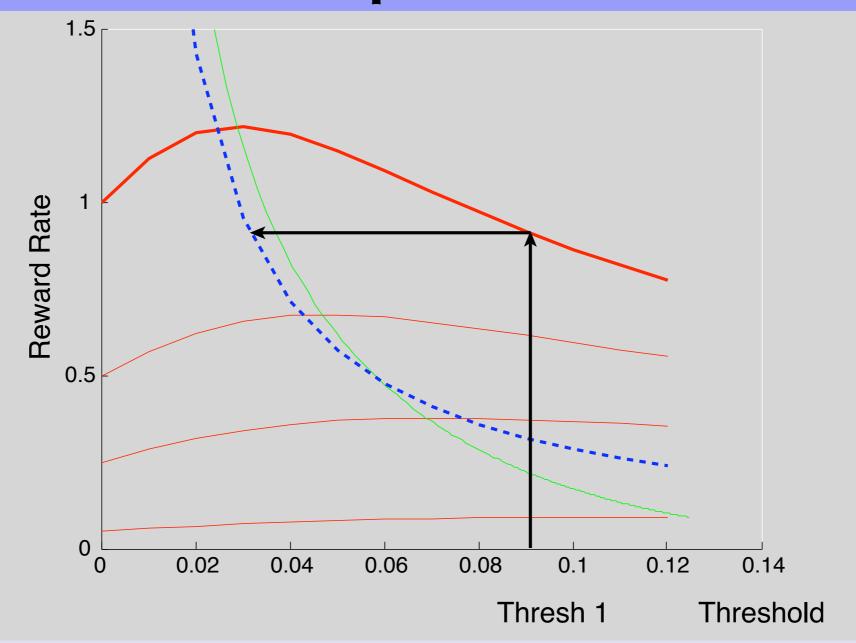


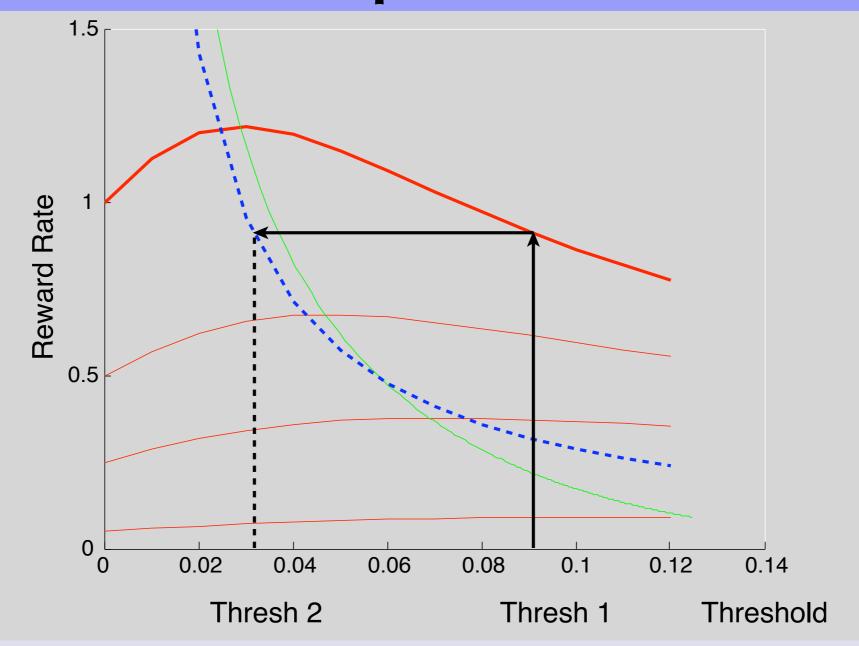
Simen, P. & Cohen, J. D. (in press), *Brain Research,* "Explicit melioration by a neural diffusion model"

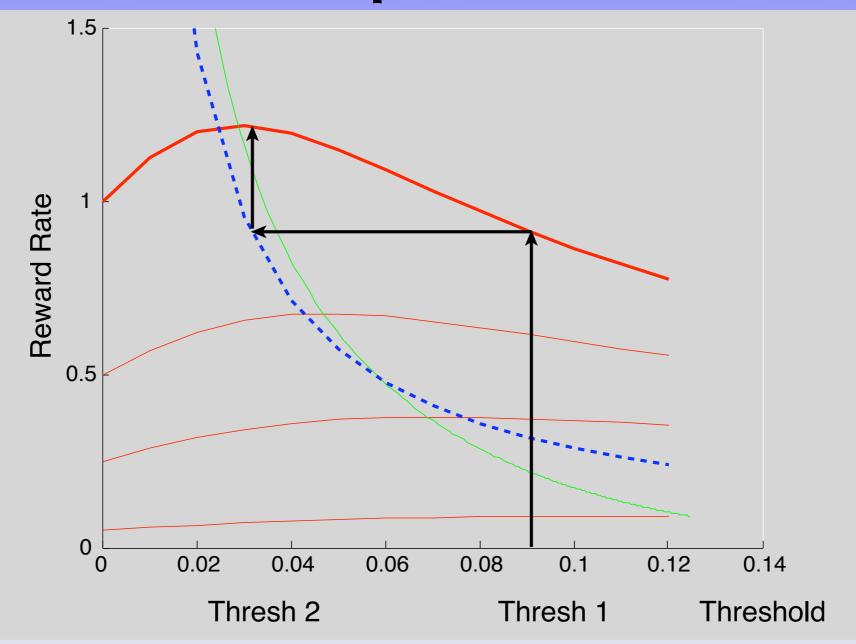
Hyperbolic function (blue) approximates envelope of optima (green) for 50:50 odds task (**Expt 1**)

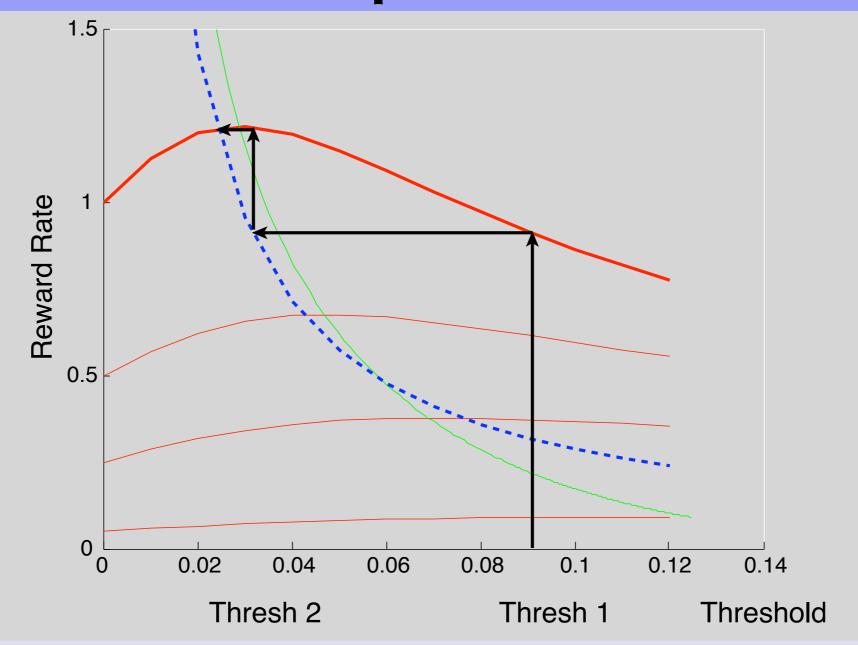


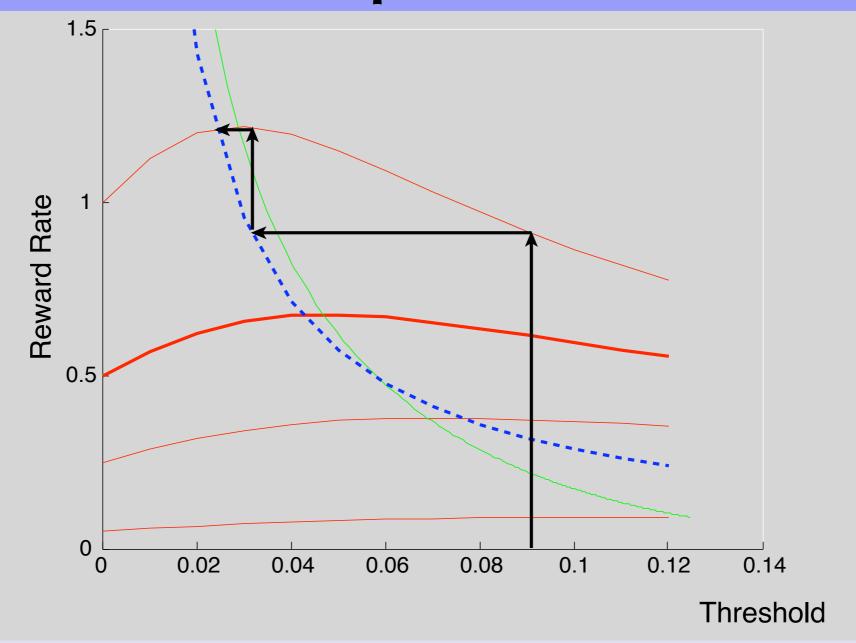


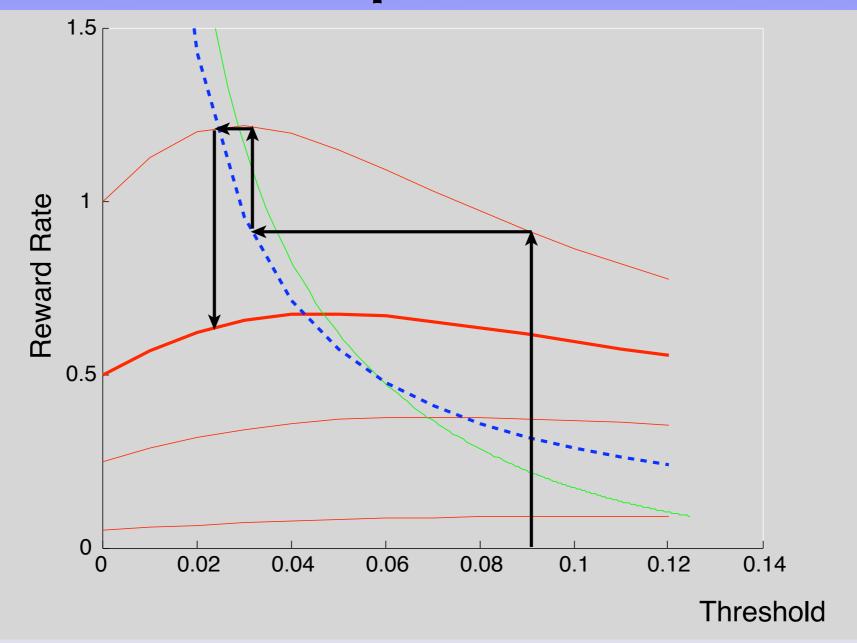


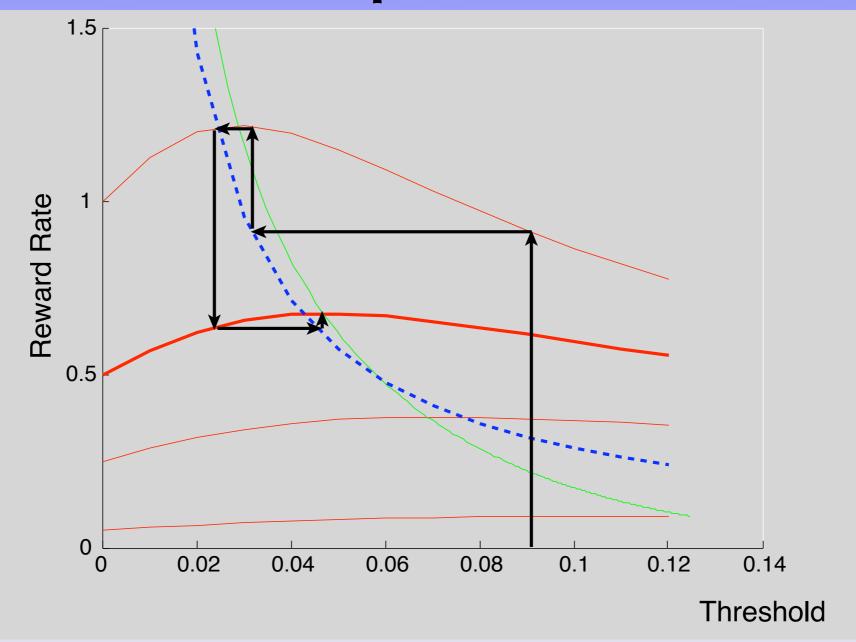


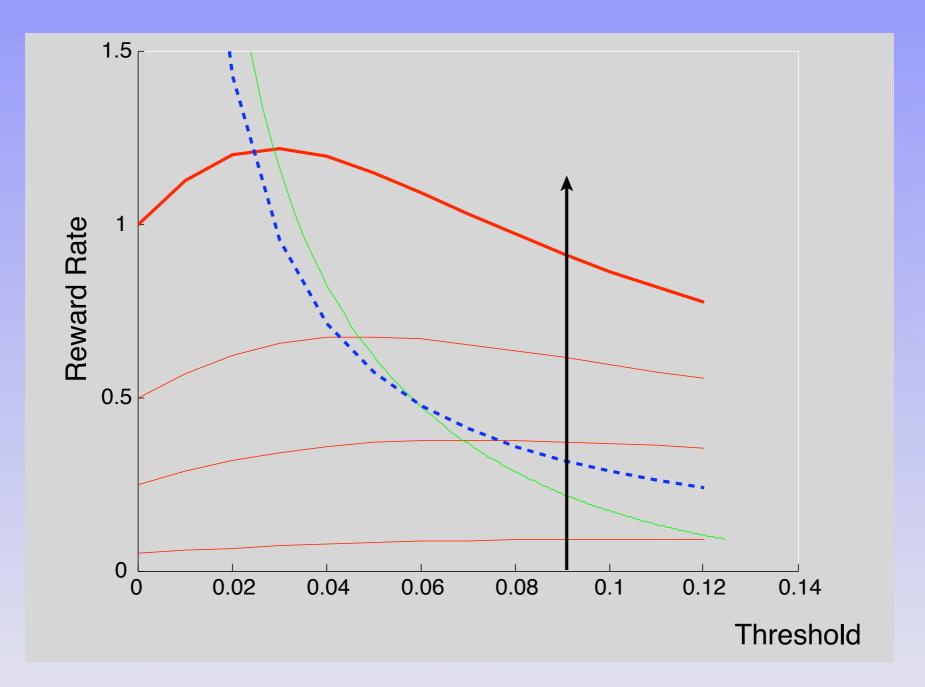


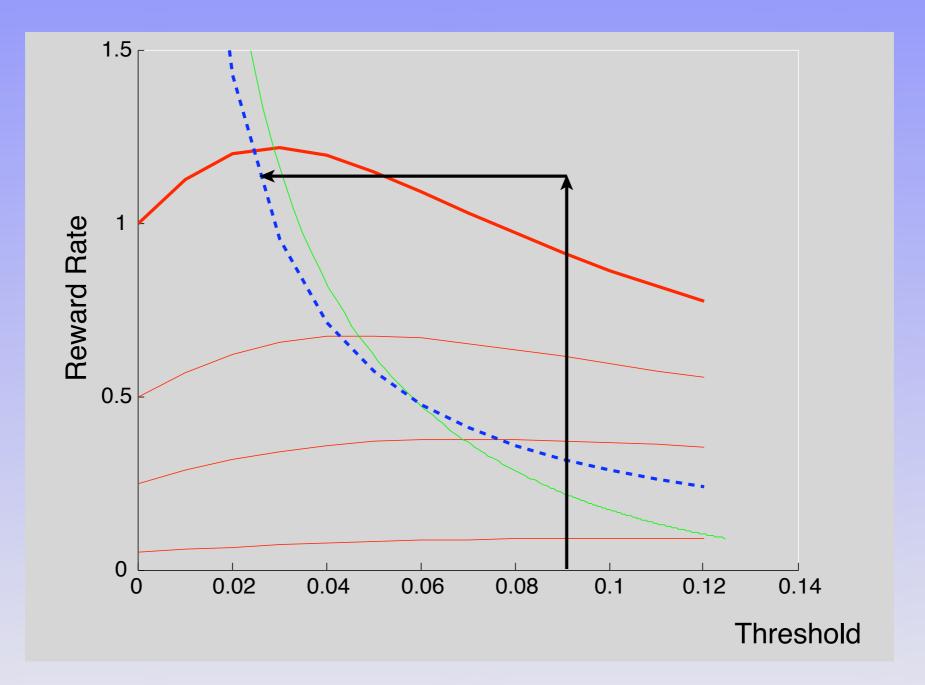


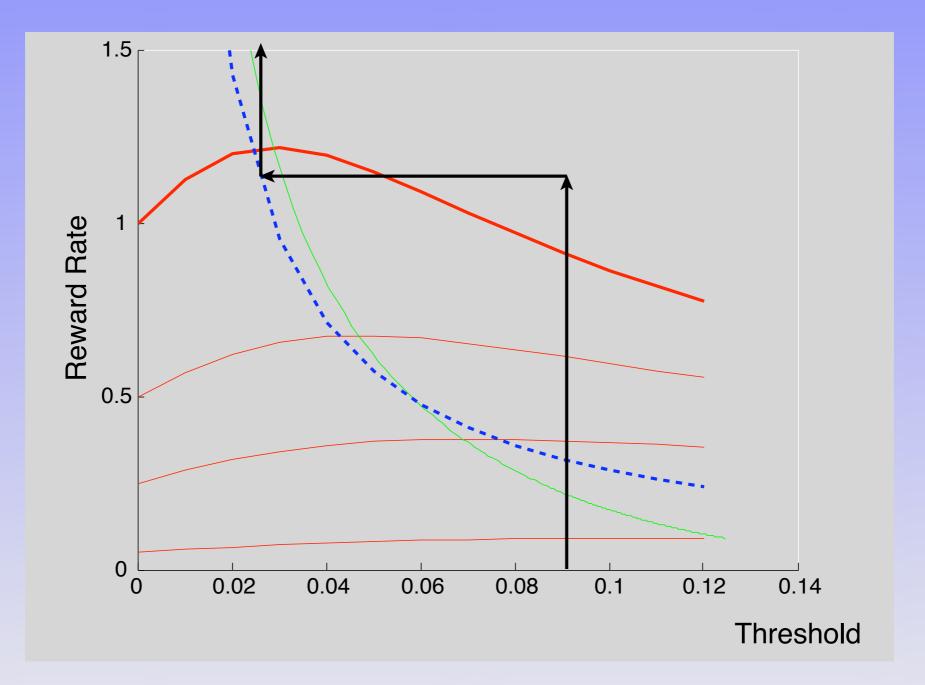


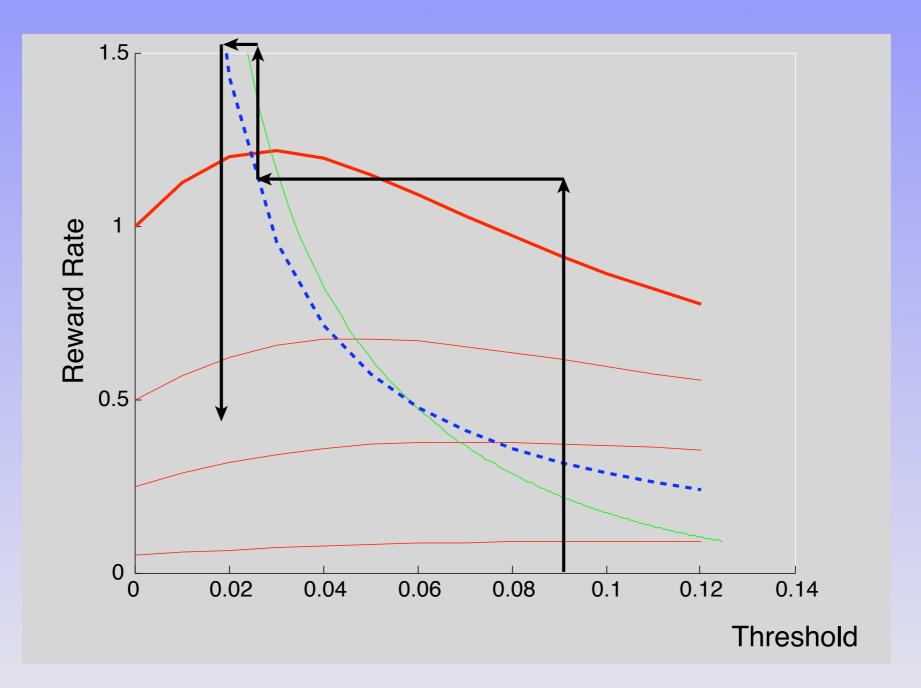


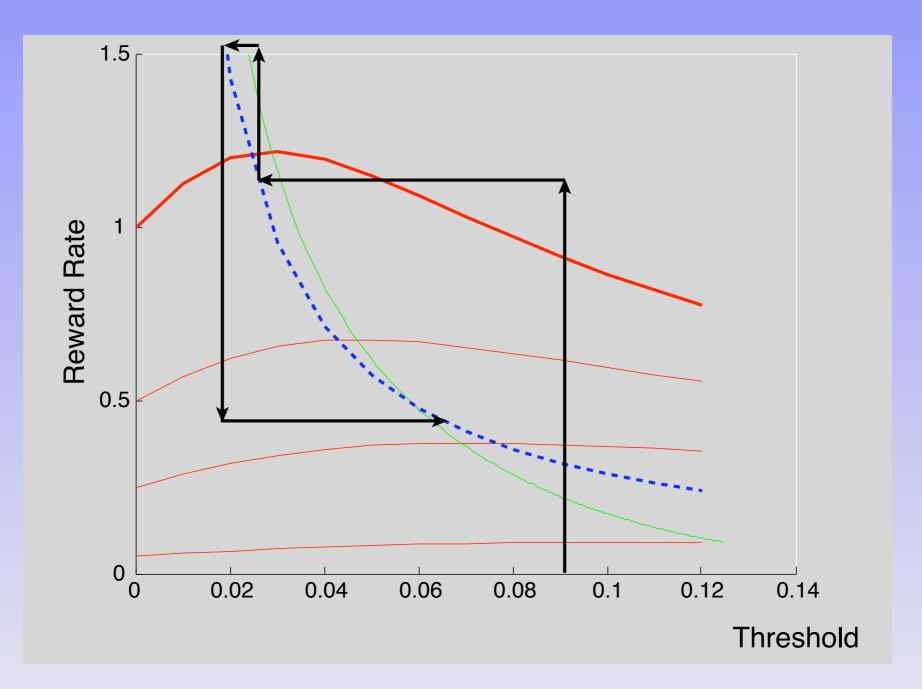


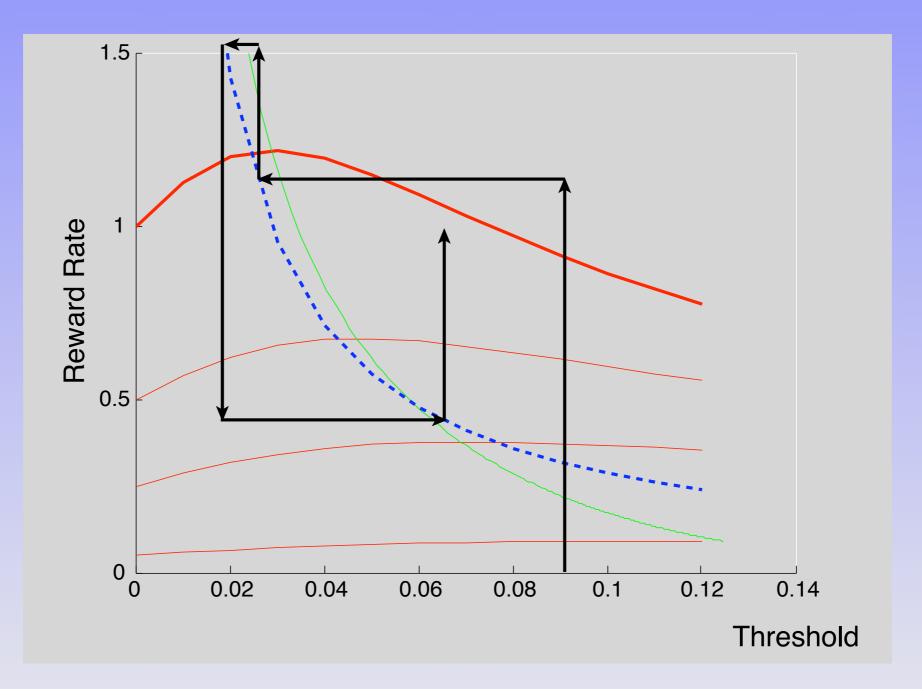


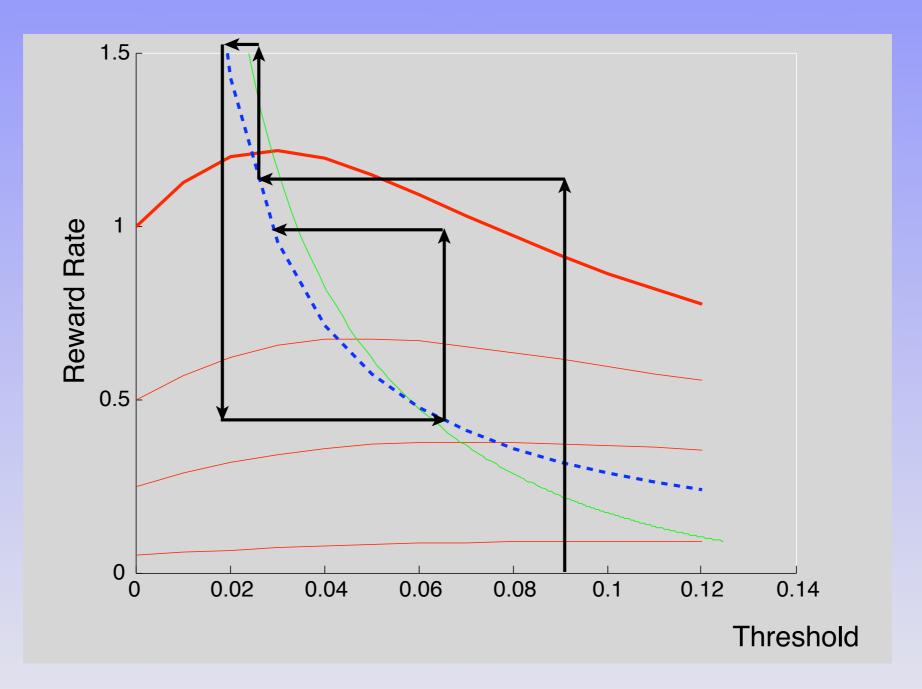


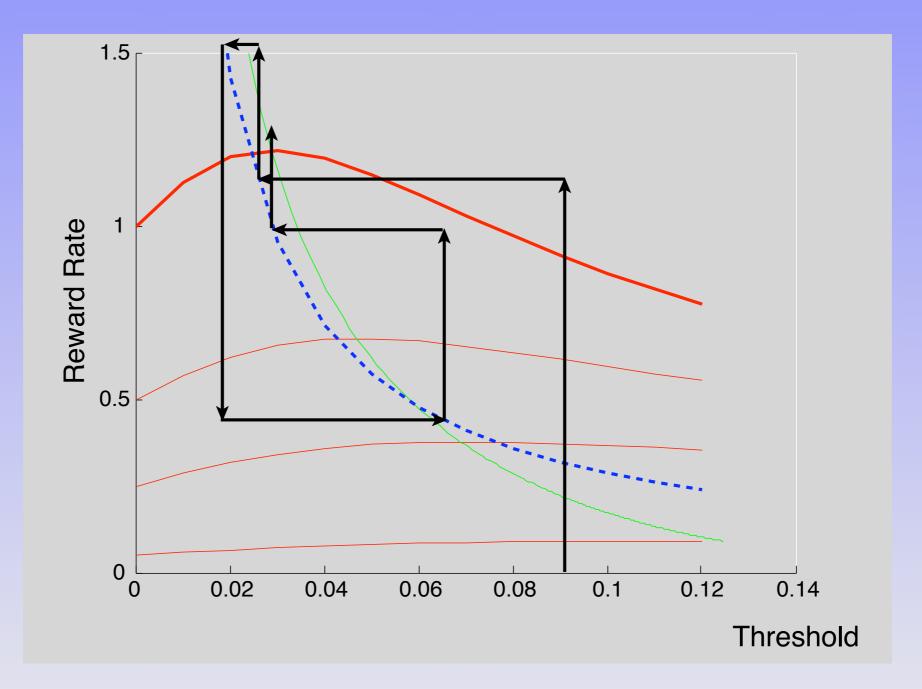


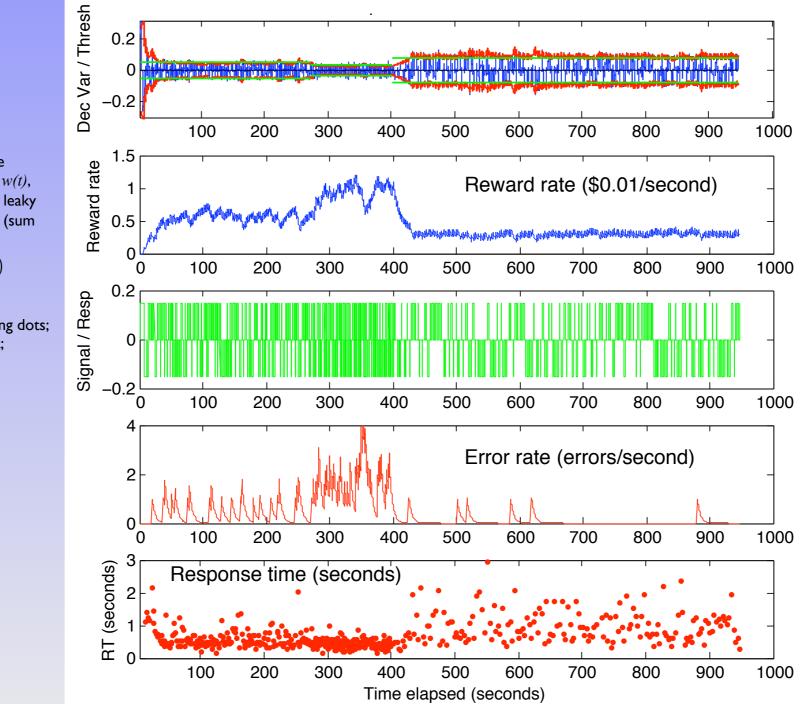










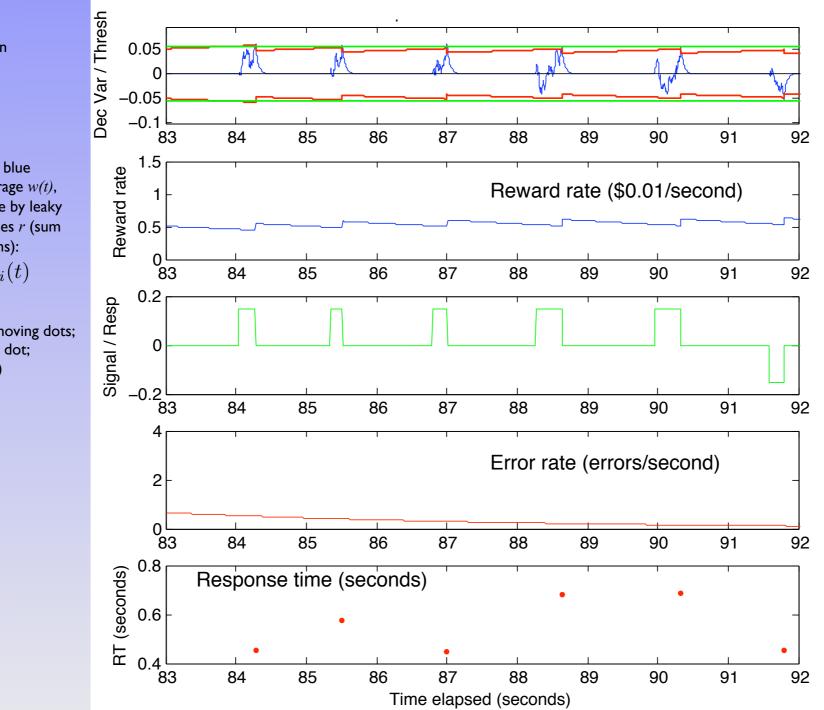


Optimal threshold – green Decision process – blue Model threshold – red

Reward rate estimate – blue Exponentially weighted average w(t), computed in continuous time by leaky integration of reward impulses r (sum of Dirac delta functions):

 $\dot{w}_i = -w_i(t) + r_i(t)$

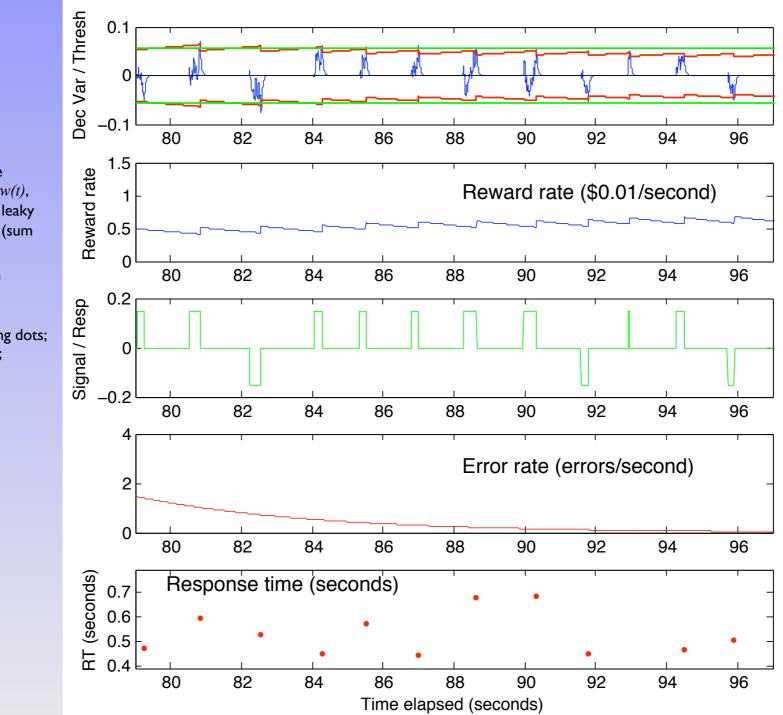
Signal – green (0.15: leftward moving dots; -0.15: rightward moving dot; 0: no signal present)



Optimal threshold – green Decision process – blue Model threshold – red

Reward rate estimate – blue Exponentially weighted average w(t), computed in continuous time by leaky integration of reward impulses r (sum of Dirac delta functions): $\dot{w}_i = -w_i(t) + r_i(t)$

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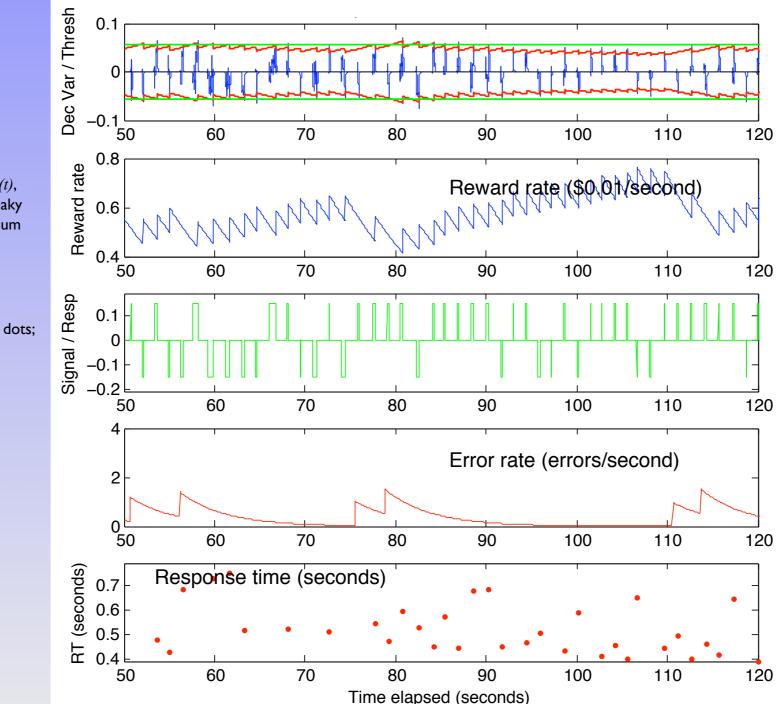


Optimal threshold – green Decision process – blue Model threshold – red

Reward rate estimate – blue Exponentially weighted average w(t), computed in continuous time by leaky integration of reward impulses r (sum of Dirac delta functions):

 $\dot{w_i} = -w_i(t) + r_i(t)$

Signal – green (0.15: leftward moving dots; -0.15: rightward moving dot; 0: no signal present)

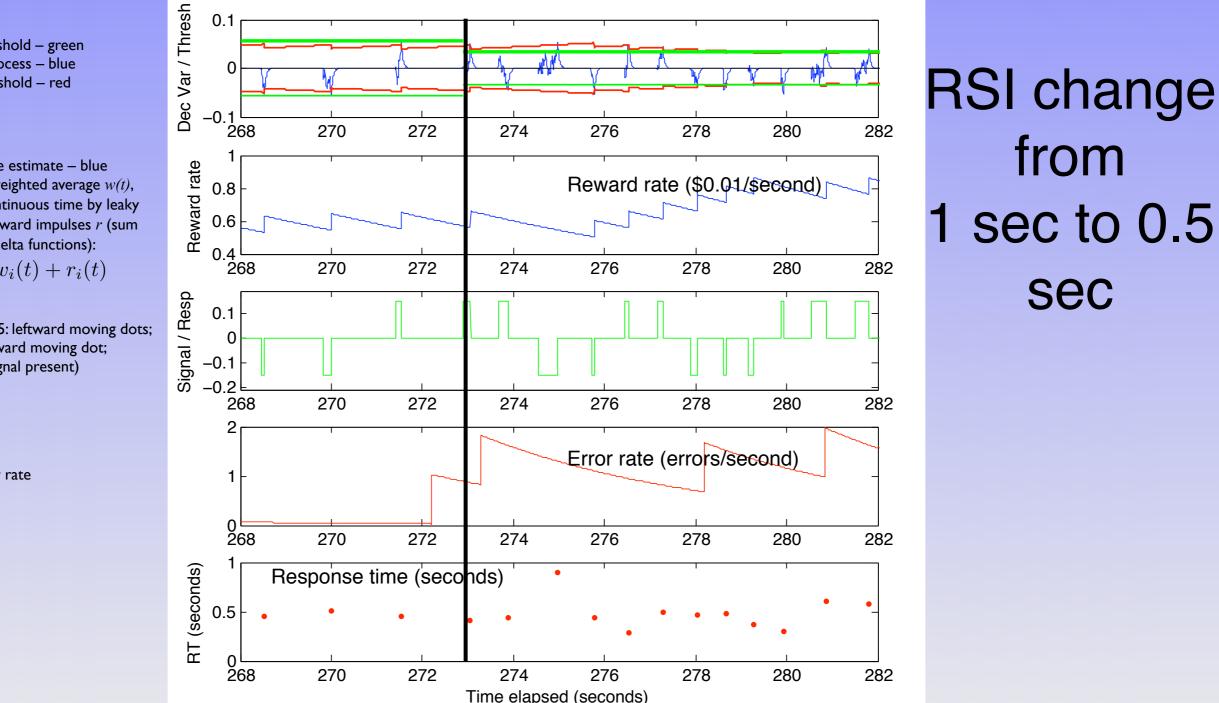


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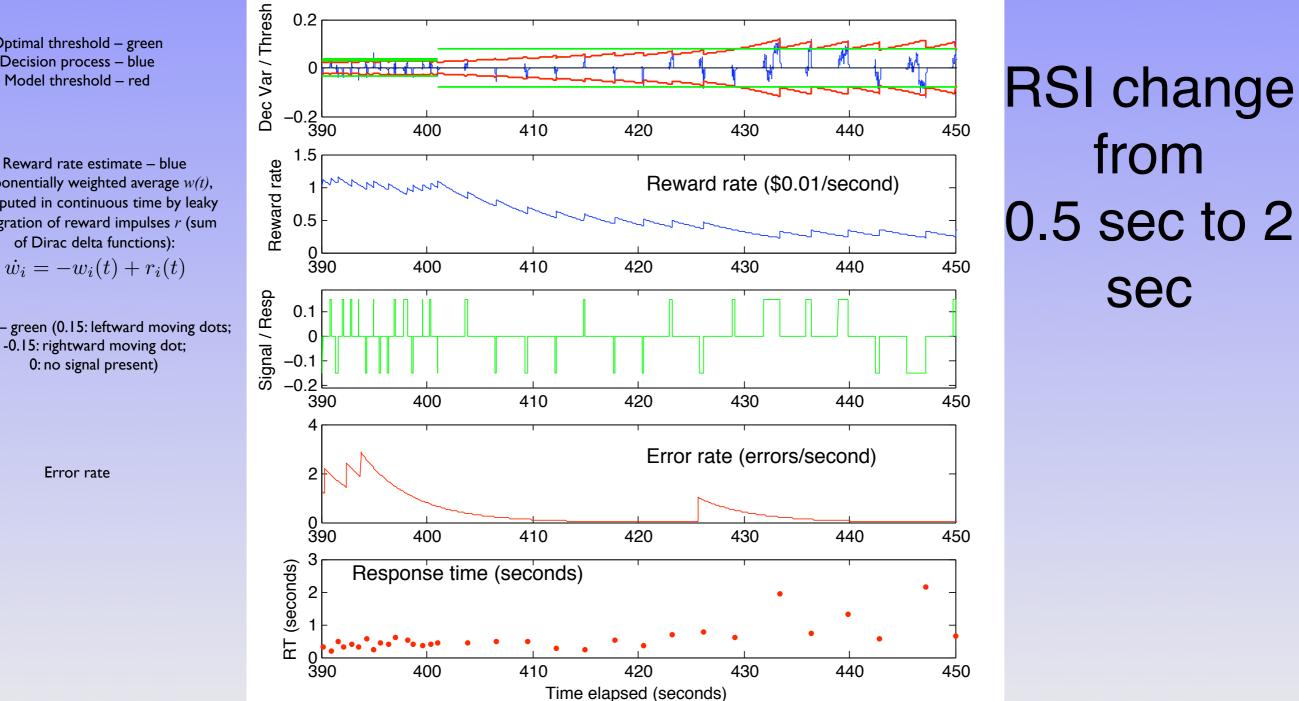


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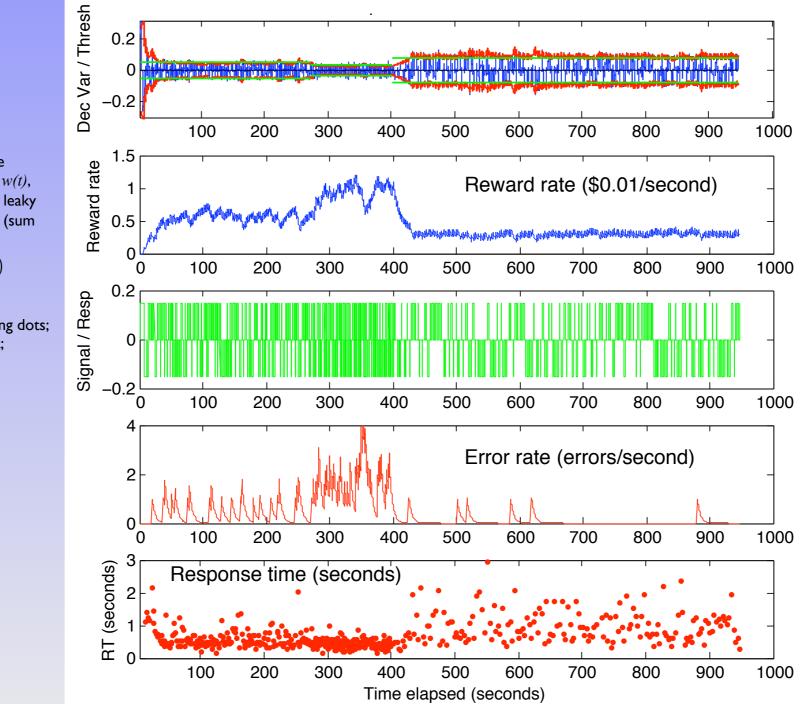
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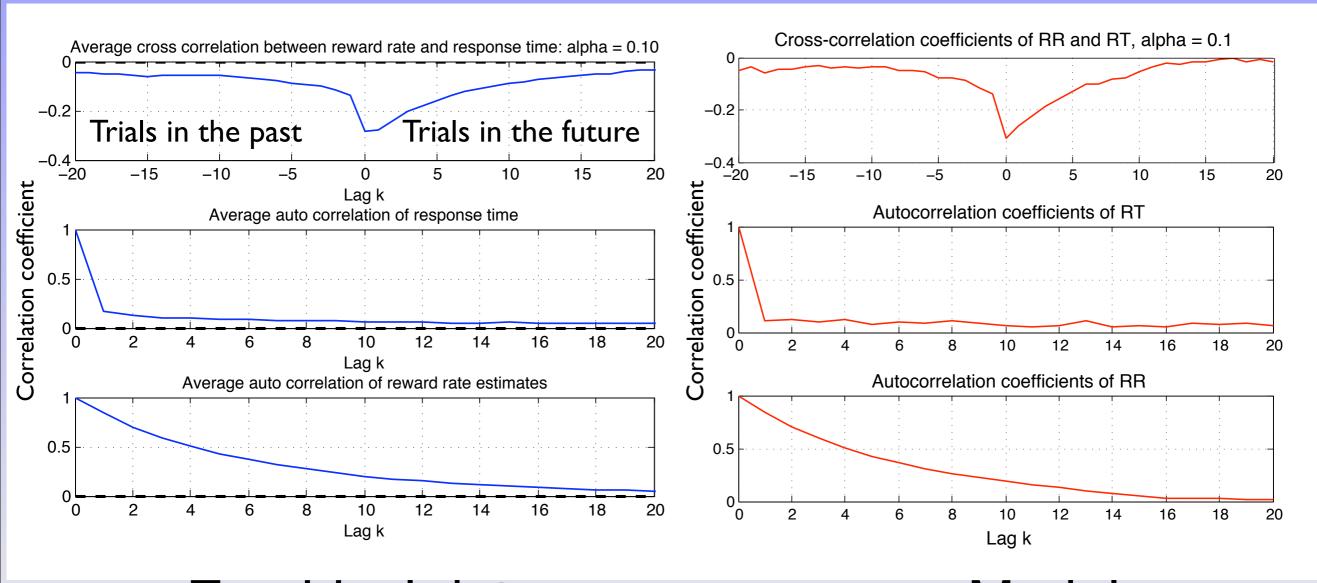
Optimal threshold – green Decision process – blue Model threshold – red

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Signal – green (0.15: leftward moving dots; -0.15: rightward moving dot; 0: no signal present)

Reward/RT cross-correlation and RT autocorrelation across trials



Empirical data

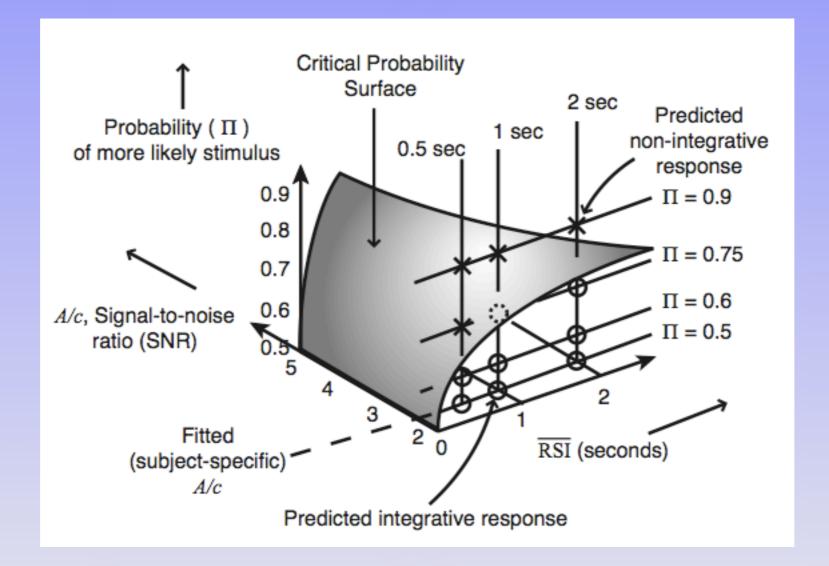
Conclusions

- Behavioral predictions of Bogacz et al. (2006) were borne out (see Simen et al., in press, JEP:HPP; also Bogacz et al., in press, Quarterly J of Euro Psych)
- Fast, nearly optimal adaptation to RSI changes, and autocorrelation in RT, can be explained by exponentially averaging rewards, then setting thresholds inversely proportional to reward rate
- Stochastic gradient ascent can be used over a longer time scale to learn the proportionality constant

Thanks to

- Jonathan D. Cohen
- Phil Holmes
- National Institute of Mental Health

Biased responding (unequal stimulus odds) creates a surface dividing integrative from non-integrative (fast-guess) responding



Bogacz, Moehlis, Brown, Holmes, Cohen (2006) Psych Review