

# Numerical analysis of network dynamics of HH neurons

Yi Sun

David Cai, Adi Rangan, Douglas Zhou

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# Outline

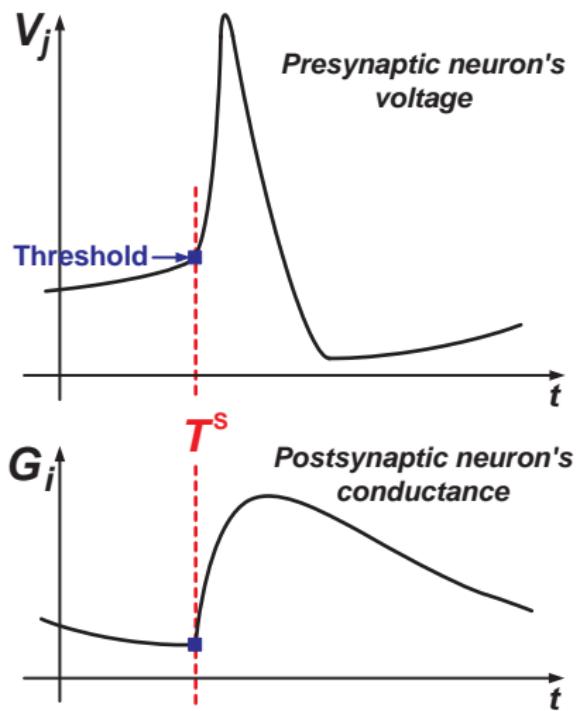
- ▶ Conductance-based Hodgkin-Huxley neurons
- ▶ Numerical results — **Chaotic regimes**
- ▶ Lyapunov exponents
- ▶ Summary

## Conductance-based Hodgkin-Huxley neurons

- ▶  $C_m \frac{d}{dt} V_i(t) = -G_{\text{Na}} m^3 h (V_i(t) - E_{\text{Na}}) - G_{\text{K}} n^4 (V_i(t) - E_{\text{K}})$   
 $- G_{\text{L}} (V_i(t) - E_{\text{L}}) - \sum_{\text{Q}} G_i^{\text{Q}}(t) (V_i(t) - E^{\text{Q}})$
- ▶  $\frac{dm}{dt} = \alpha_m(V_i)(1-m) - \beta_m(V_i)m$
- ▶  $\frac{dh}{dt} = \alpha_h(V_i)(1-h) - \beta_h(V_i)h$
- ▶  $\frac{dn}{dt} = \alpha_n(V_i)(1-n) - \beta_n(V_i)n$
- ▶  $\frac{d}{dt} G_i^{\text{Q}}(t) = -\frac{G_i^{\text{Q}}(t)}{\sigma^G} + H_i^{\text{Q}}(t)$
- ▶  $\frac{d}{dt} H_i^{\text{Q}}(t) = -\frac{H_i^{\text{Q}}(t)}{\sigma^H} + \sum_{j \neq i} \sum_k S_{i,j}^{\text{Q}} \delta(t - T_{j,k}^S) + \sum_k F_i^{\text{Q}} \delta(t - T_{i,k}^F)$

# Conductance $G$ : voltage-threshold model

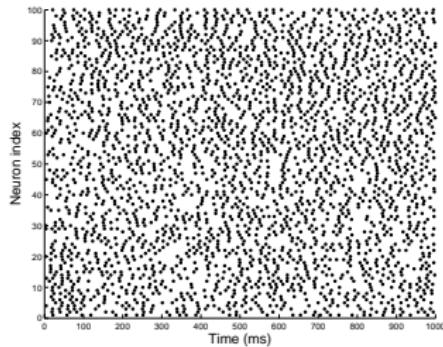
- ▶  $\frac{d}{dt} H_i^Q(t) = -\frac{H_i^Q(t)}{\sigma^H} + \sum_{j \neq i} \sum_k S_{i,j}^Q \delta(t - T_{j,k}^S) + \sum_k F_i^Q \delta(t - T_{i,k}^F)$
- ▶  $\frac{d}{dt} G_i^Q(t) = -\frac{G_i^Q(t)}{\sigma^G} + H_i^Q(t)$
- ▶  $\sigma_G = 0.5\text{ms};$
- ▶  $\sigma_H = 3.0\text{ms};$
- ▶ Threshold:  $V_{th} = -43\text{mV};$
- ▶ Other parameters: standard values in book [Dayan & Abbott, 2001]
- ▶ Numerical method: Runge-Kutta 4th order ODE solver with fast spike-spike correction algorithm in [Rangan & Cai, JCN 2007]



# Numerical errors of different coupling strength $S$

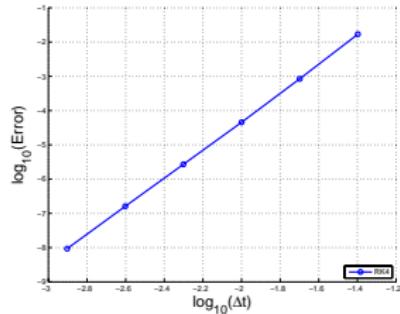
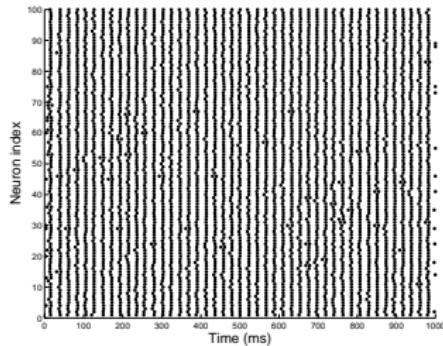
- Take  $Y(t) = (V_1, m_1, h_1, n_1, G_1, H_1, \dots, V_N, m_N, h_N, n_N, G_N, H_N)'$  with  $N = 100$
- Numerical error  $E(t) = \| Y^{\text{exact}}(t) - Y^{\Delta t}(t) \| = \sqrt{\sum_i (y_i^{\text{exact}}(t) - y_i^{\Delta t}(t))^2}$

- $S = 0.2$   
Asynchronous  
case;

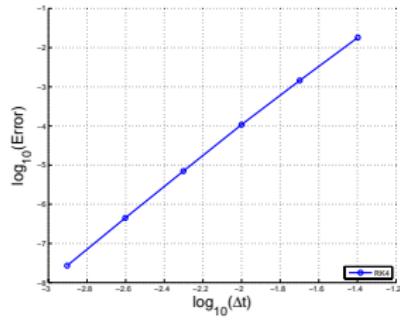


- $\Delta t : 0.04\text{ms}$   
 $\rightarrow 0.00125\text{ms};$

- $S = 0.8$   
Synchronous  
case;

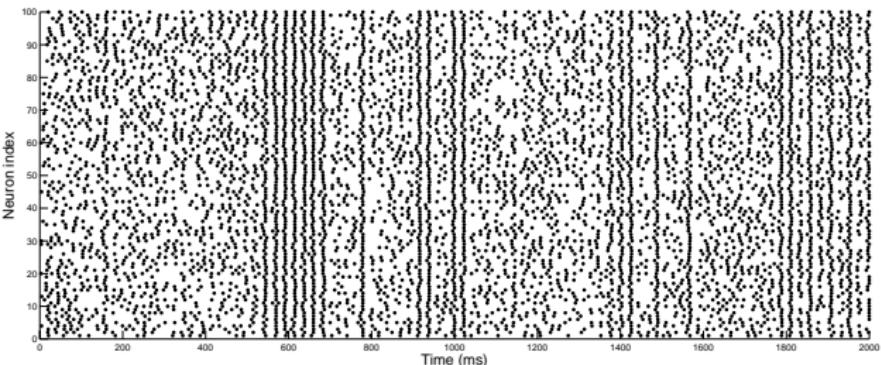
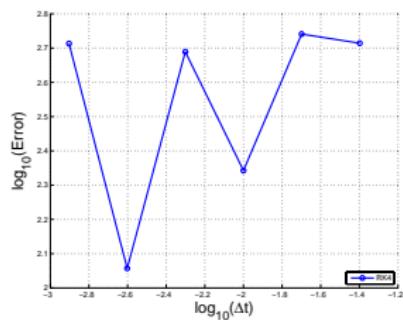


slope = 4

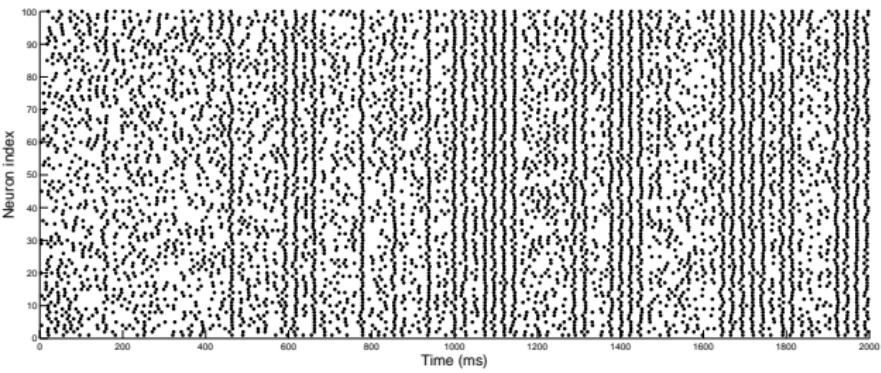


# Co-existent case: $S = 0.35$ : No numerical convergence!

- $\Delta t = 0.04\text{ms}$ ;

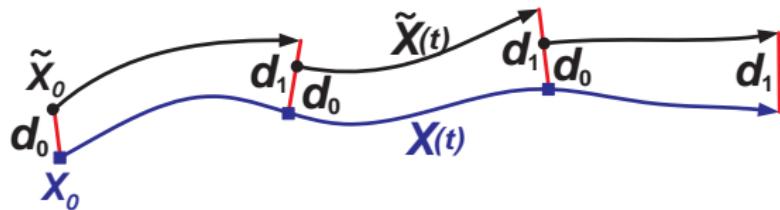


- $\Delta t = 0.02\text{ms}$ ;



# Numerical calculation of largest Lyapunov exponent

- ▶ Examine  $X(t) = (V_1, m_1, h_1, n_1, G_1, \dots, V_N, m_N, h_N, n_N, G_N)'$ , state vector of **continuous** variables;
- ▶ Select two very nearby points  $\tilde{X}_0$  and  $\tilde{X}_0$  separated by  $d_0$  as initial conditions, (e.g  $d_0 = 1.0\text{e-}8$ );
- ▶ Advance both trajectories  $X(t)$  and  $\tilde{X}(t)$  for time interval  $dt_{norm}$  and calculate the new separation  $d_1(t)$ ;
- ▶ (**Re-normalization**): Re-adjust one trajectory so the separation is  $d_0$  in the same direction as  $d_1(t)$ :  $\tilde{X}(t) = X(t) + d_0 \frac{(X(t) - \tilde{X}(t))}{d_1(t)}$ ;

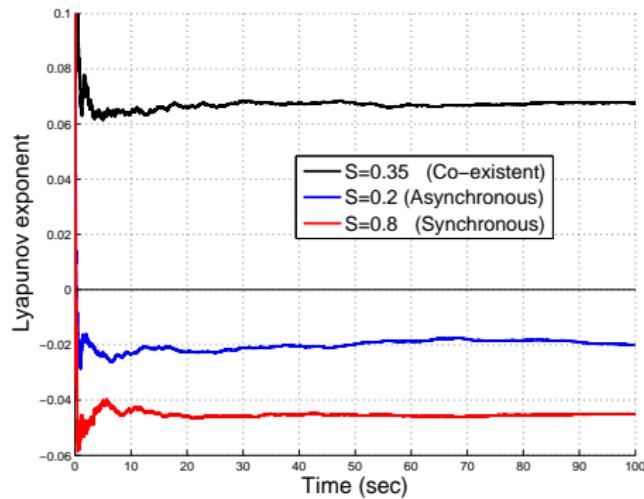


- ▶ Largest Lyapunov exponent:  $\lambda = \lim_{M \rightarrow \infty} \frac{\sum_{k=1}^M \ln \left( \frac{d_1(t_k)}{d_0} \right)}{M dt_{norm}}$ , where  $M$  is the total number of steps for doing re-normalization and  $t_k = k dt_{norm}$ .

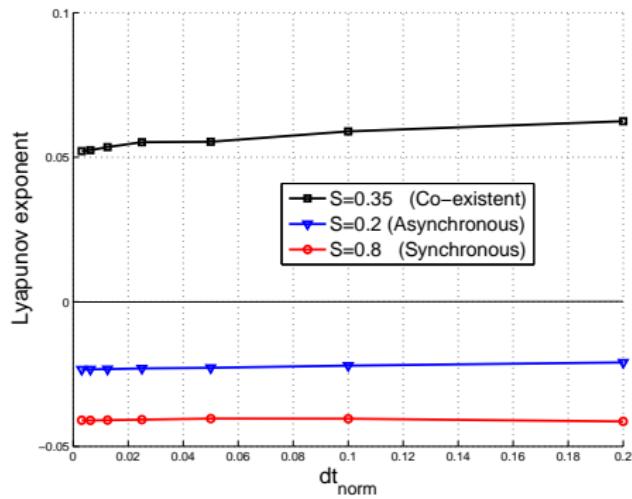
# Lyapunov exponent: numerical test

- ▶ Feedforward input strength:  $F = 0.1$ ; Input rate  $r = 50$  spikes/sec.
- ▶  $S = 0.2$ : Asynchronous case,  $\lambda = -0.0199$ ;
- ▶  $S = 0.35$ : Co-existent case,  $\lambda = 0.0676$ ;
- ▶  $S = 0.8$ : Synchronous case,  $\lambda = -0.0450$ ;

Lyapunov exponent trace



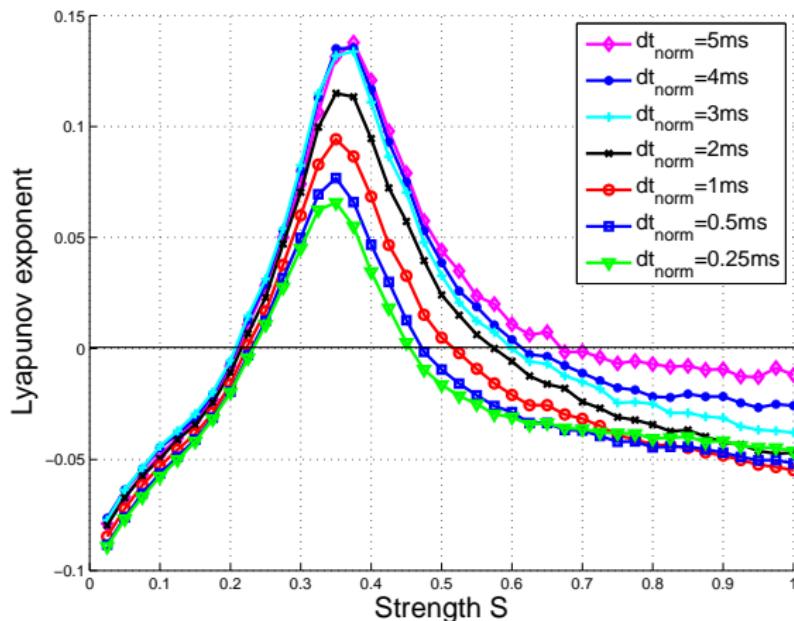
Lyapunov exponent convergence



# Lyapunov exponent: numerical test

- ▶ Feedforward input strength:  $F = 0.1$ ; Input rate  $r = 50$  spikes/sec.
- ▶ Running time:  $T = 100$ sec; ODE step:  $\Delta t = 0.04$ ms.

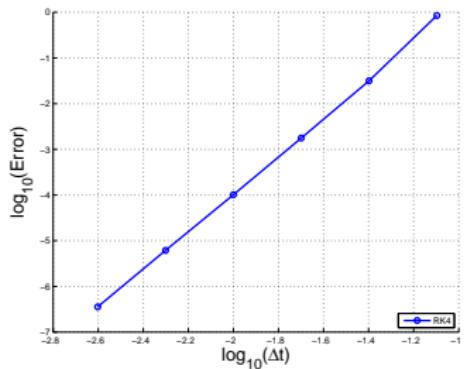
Strength S scan result



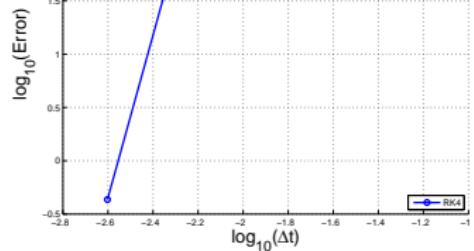
# Lyapunov exponent: numerical test

$$T = 10\text{sec}, \lambda = 0.01522$$

►  $S = 0.260$ ;

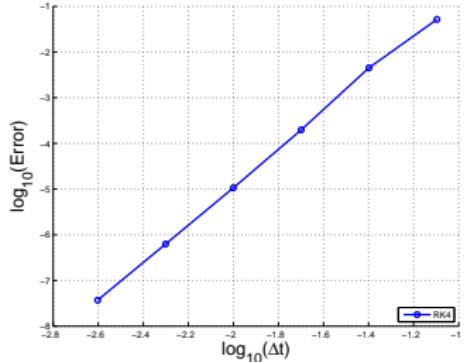


$$T = 100\text{sec}, \lambda = 0.01589$$

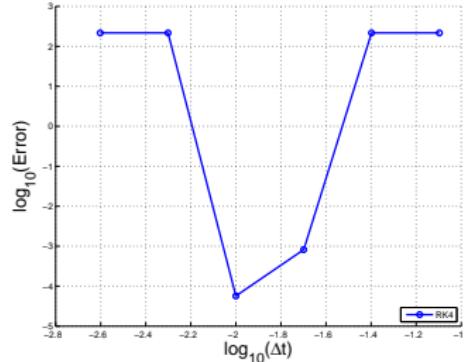


$$T = 10\text{sec}, \lambda = -0.00789$$

►  $S = 0.456$ ;



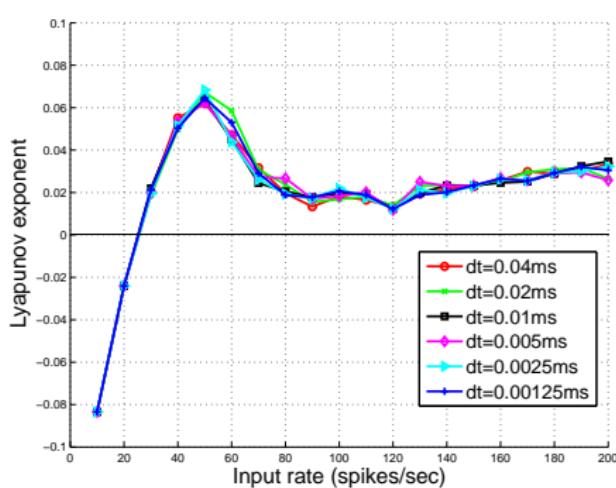
$$T = 100\text{sec}, \lambda = -0.00216$$



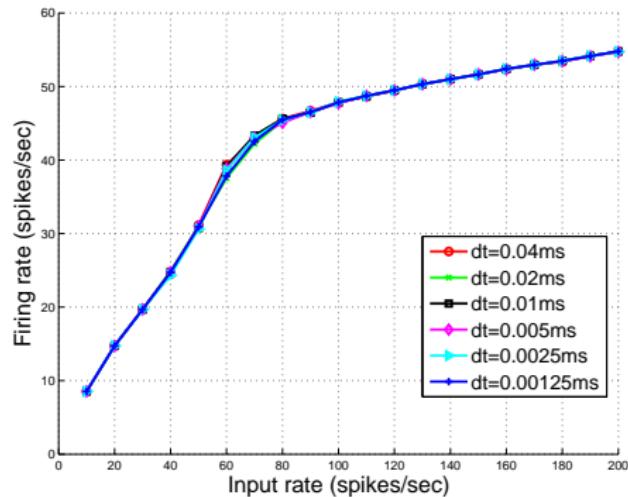
# Lyapunov exponent: numerical test

- ▶ Running time:  $T = 100\text{sec}$ ; Feedforward input strength:  $F = 0.1$ ;
- ▶ Cortical coupling strength:  $S = 0.35$  (Co-existent case);
- ▶ Scan input rate from  $r = 10$  to  $r = 200$  spikes/sec.
- ▶ Vary ODE step from  $\Delta t = 0.04$  down to  $0.00125\text{ms}$ ; fix  $dt_{norm} = 0.16\text{ms}$ .

Lyapunov exponent convergence

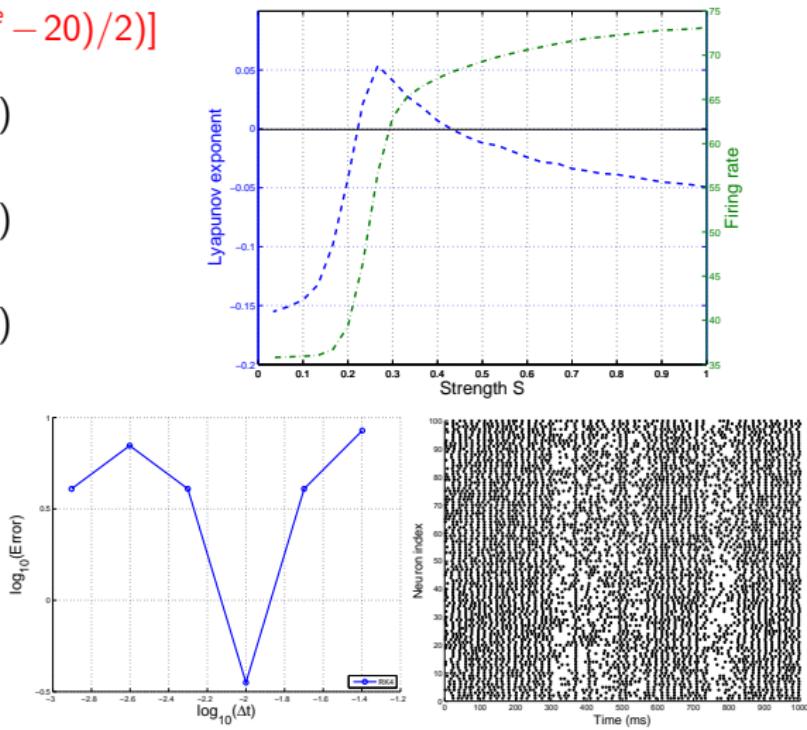


Firing rate statistically correct



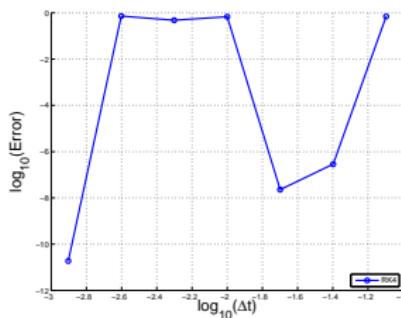
# Extensions 1: conductance $G_4$ depends on voltage continuously

- ▶  $\frac{d}{dt} G_{4i}(t) = -\frac{G_{4i}(t)}{\sigma} + \sum_{j \neq i} S_{i,j}^E g(V_j^{pre}) + \sum_k F_i^Q \delta(t - T_{i,k}^F)$
- ▶  $g(V_j^{pre}) = 1/[1 + \exp(-(V_j^{pre} - 20)/2)]$
- ▶  $\frac{d}{dt} G_{3i}(t) = -\frac{G_{3i}(t)}{\sigma} + G_{4i}(t)$
- ▶  $\frac{d}{dt} G_{2i}(t) = -\frac{G_{2i}(t)}{\sigma} + G_{3i}(t)$
- ▶  $\frac{d}{dt} G_{1i}(t) = -\frac{G_{1i}(t)}{\sigma} + G_{2i}(t)$
- ▶  $\frac{d}{dt} G_i(t) = -\frac{G_i(t)}{\sigma} + G_{1i}(t)$
- ▶  $\sigma = 0.5\text{ms};$
- ▶  $S = 0.26$ : Co-existent case,  
 $\lambda = 0.05359$ ;  $T = 10\text{sec}$

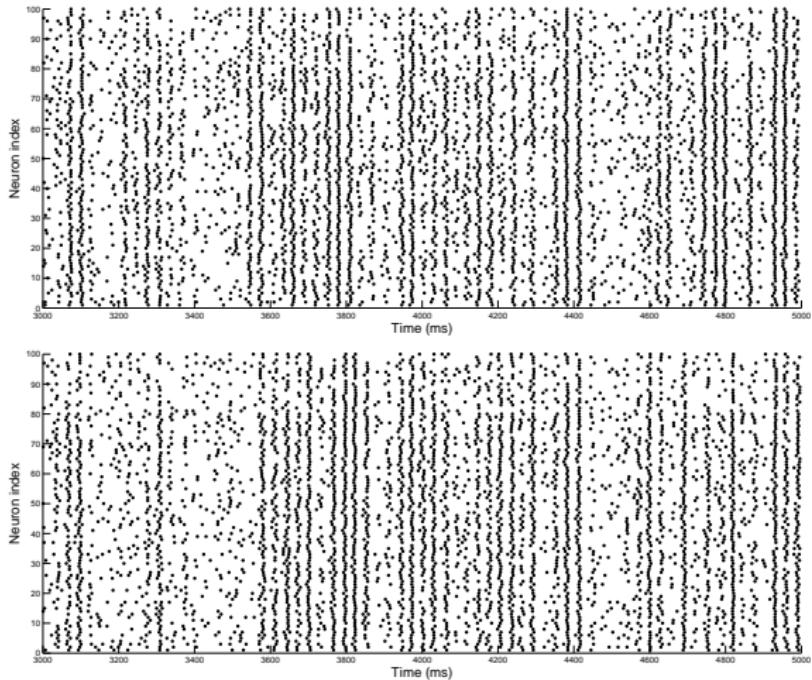


## Extensions 2: add in the inhibitory neurons

- ▶  $N^E = 80$  excitatory neurons;  $N^I = 20$  inhibitory neurons;
- ▶  $\sigma_G^E = 0.5\text{ms}$ ;  $\sigma_H^E = 3.0\text{ms}$ ;  $\sigma_G^I = 0.5\text{ms}$ ;  $\sigma_H^I = 7.0\text{ms}$ ;
- ▶  $S^{EE} = 0.6$ ;  $S^{IE} = 1.0$ ;  $S^{EI} = 0.1$ ;  $S^{II} = 2.0$ ;
- ▶  $\Delta t = 0.04\text{ms}$ ,  
 $\lambda = 0.05263$ ;



- ▶  $\Delta t = 0.02\text{ms}$ ,  
 $\lambda = 0.05059$ ;



## Summary

- ▶ In some parameter regime, we can not get numerical convergence for individual neuronal trajectories;
- ▶ These **chaotic** regimes may be indicated by **positive** largest Lyapunov exponent of the continuous system variables;
- ▶ Some statistical properties (e.g. average system firing rate) may have numerical convergence.
- ▶ On-going work: try to use some tools (return plots of system ISI, power spectra analysis of voltage traces, etc) to distinguish these regimes intuitively.

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